INDUSTRIAL WEIGHING SOLUTION ${ }^{\top M}$

## EXI-200AD

## Explosion proof Indicator



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## Cautions for Your Safety

'Please comply with 'Cautions for Your Safety', which will lead you to use the product safely and properly to prevent any dangerous situations.

- Cautions are divided into 'Warning' and 'Alert', which mean as follows.
- Keep this manual in a place where product users can find out, after finish reading it.

'Alert' means a great possibility led to the injury or material damage when instructions are violated.


## (!) Warning

| Never disassemble, repair or retrofit the |
| :--- |
| product. |
| It might exclude the product |
| from the quality assurance and cause |
| the damage to devices, electric shock or |
| fire. |
| inserted to prevernt shaking. |
| Any instable connection might cause |
| electric sparks to set fire. |


| Ensure the grounding of the product. |
| :--- |
| electric shock upon electric leak. |

Do not damage, process,
excessively jerk, bend or twist the
power cord.
It might damage the power cord to
cause fire or electric shock.

## Attention



## 1. Normal Requirements

### 1.1 Application Range

This product is an explosion-proof and dust ignition-proof product for locations of gas, steam or chemical use and other hazardous areas.

■ Explosion-proof Structure and Class

|  | Explosion proof | Dust ignition proof |
| :---: | :---: | :---: |
| Explosion- <br> Proof Class | Ex d IIB $+\mathrm{H}_{2}$ T6 IP66 | Ex tD A21 $85^{\circ} \mathrm{C}$ IP66 |
| Gas group | IIB and $\mathrm{H}_{2}$ (hydrogen region) |  |
| Temp Class | T6 $\left(85^{\circ} \mathrm{C}\right)$ |  |

### 1.2 Transport, assembly and installation

### 1.2.1. Transport

(1) Packaging method and specification
(a) After removing any external/internal foreign matter on the product, clean, dry and apply corrosion preventive treatment on exposed sections.
(b) Measures are needed to prevent foreign matter from entering openings within the product.
(c) The packaging must correspond with the size and weight of the contents, and internal fillings that can act as a buffer must be used such as air caps or newspapers.
(d) The product must be appropriately protected to prevent rust and corrosion.
(2) Transport Method

If stacked high during transportation, there is possibbility of damage by fall due to the weight of the product. Therefore suitable protective equipment or devices must be used when transporting.

### 1.2.2. Assembly and Installation

## (1) Assembly

This product is fully assembled when shipped and there is no need of separate assembly by the user.

## (2) Installation

When installing electrical instruments in an explosion-proof area, compare the below requirements with the technical specifications beforehand to confirm correspondence.
(a) Normal Requirements.
(1) Use installation method (floor installation, wall installation etc.) and installation form (slope allowance etc.) that is appropriate with the explosion prevention electric instrument's usage conditions.
(2) Bolts, nuts, metallic etc. used in the installation must have sufficient mechanical strength. Also, use materials and surface treatment that is clearly based on installation location.
(3) Ensure recharge sections are not exposed.
(b) Installation Location
(1) Install where it is convenient to operate, manipulate, adjust, maintain etc.
(2) If possible avoid locations exposed to moisture or humidity and avoid high humidity areas.
(3) If possible avoid areas of corrosive liquid dispersion and near release of corrosive gas.
(4) Avoid locations close to high temperature heating elements such as heat pipes, steam pipe etc. and areas of rapid temperature fluctuation.
(5) Avoid locations that is heavily affected by vibrations from mechanical devices etc.
(6) Do not install in locations of high pressure or heavy electric noise.
(7) Do not install in location of strong direct sunlight.
(c) Installation method must be suitable to the purpose.
(d) Power connection and wiring.
(1) Use a cable with internal ground wire for the power line and install separately from the signal line.
(2) Connect the power cord with the power socket in an explosion proof area and when connecting in an explosive area always connect using "plugs and receptacles'.
$\Delta$
(3) Connect the power and signal lines through a designated location. (Refer to 4.2.2)
(e) Wiring Method during Installation (power and load cell)
(1) Refer to "4. External Explanation" and "5. Internal Explanation" of this manual.
(2) Use an Allen wrench to loosen the front bolts and open the front cover

(3) Connect an appropriate cable gland (joint screw diameter(M20*1.5)) to the power line. (Refer to 4.2 FrontSurface Explanation)
(4) Connect the power line to the power terminal as depicted in the figure below. Refer to this manual's "5.1.1 Power Connector" for the wiring order. (Connect the power line using a $4 \Phi$ terminal etc.)

(5) Connect an appropriate cable gland (joint screw diameter (M20*1.5)) to the load cell line. (Refer to 4.2 Front Surface Explanation)
(6) Refer to this manual's "5.1.2 Load Cell Connector" and the wiring blueprint of the load cell for the wiring order. (Connect the load cell line using pin terminals etc.)


### 1.3 Function, Operation and Use

### 1.3.1. Inspection and Adjustment

(1) For the explosion-proof instrument, check for following suitability list
(a) Terminal voltage, pole number
(b) The type and specification of replacement parts from each part
(c) Whether the overall control system (control, manipulation, display, notification etc) is working
(d) Operation and display of auxiliary instruments
(e) Presence of vibration and its intensity.
(f) Inspection of the wiring inlet.
(1) Whether metallic wiring material suitable to the conduit tube screw section specifications are used.
(2) Whether sealing has been installed on conduit cable sections requiring explosionproofing.
(3) The compound must be filled at a sufficient depth and the attachment and hardening state must be acceptable.
(4) The state of the attachment of the electronic instrument must be acceptable.
(g) Inspection of connection area between wiring and electric instrument etc.
(1) Proper access of terminal sign, polar circuits.
(2) The connection area must be sufficiently tight and measurement must be made to prevent loosening.
(3) Connection section without terminal blocks etc must be clearly insulated.
(h) Inspection of container cover
(1) There must be no damage or foreign matter on the cover access section or screw threads and it must be coated with non-hardening oils.
(2) When packing is used for dust and water proofing, it must be installed properly.
(3) The screws must not be faulty and sufficiently tightened.
(i) The state if operation based on explosion-proof structure and conditions of use must be acceptable
< Basic Inspection Items >

| Item | Method | Inspection Content | Notes |
| :---: | :---: | :---: | :---: |
| Container <br> (explosion-proof <br> box) | By eye | There must be no external damage (rust, dust) | cleaning, <br> corrosion <br> protection |
| Display window | By eye | There must be no damage by scraping etc | cleaning |
| Screws | By eye, <br> touch | There must be no loosening, dust or rust | tighten, cleaning |
| Button | By eye, <br> touch | There must be no loosening or breakage | tighten, replace |
| Power line inlet <br> Cable gland | By eye, <br> touch | There must be no damage, resolution or <br> loosening | tighten, replace |
| Electric <br> instrument (PC) | By eye | There must be no external damage and <br> damage to power status | cleaning |

### 1.3.2. Operation

(1) Operation Method
(a) Check the cable connection and metallic wiring state of the installed product.
(b) Apply power to the installed product.
(c) Check if it is functioning normally.
(2) Operation Cautions and Prohibitions
(a) Before using the product the learn user manual and use and install according to the given method.
(b) This product must be constructed by qualified expert electrical construction personnel.

### 1.4 Maintenance and Cautions

### 1.4.1. Maintenance

(1) This product requires continued management through periodic inspection (1 time or more per month recommended).
(2) When maintaining electrical instruments the following items must be checked.
(a) There must be no damage to the container connection surface (screw).
(b) There must be no damage or cracks from shock to the container exterior.
(c) The screws must be uniform and sufficiently tight.
(d) Corrosion prevention treatment must have been sufficiently carried out to prevent rust on the container connection surface or exterior.

### 1.4.2. Preparations

(1) Prepare tools, materials, replacement etc.
(2) Determine and check the need for insulation and insulation range.
(3) Check the presence of explosive gas and handle as a non explosion-proof area.
(4) Operator knowledge and capacity.
(5) Documents and diagrams related to the explosion prevention area (division diagram etc.).

### 1.4.3. Cautions

(1) When inspecting during application of current, the body (cover) of the explosion-proof electrical instrument must not be opened.
(2) When maintaining in an explosion-proof area, ensure no shock sparks occur from tools etc.
(3) When maintaining and repairing, disassembly and assembly work related to the electrical instrument's explosion-proof capacity is accompanied. Therefore the explosion-proof capacity must be checked for all parts.
※ If the user cannot maintain or determine cause of failure, please contact the manufacturer. (Contact numbers are included in the back of the manual)

## 2. Technical Specifications

### 2.1 Product Specifications

| Product Name | Indicator |  |  |
| :---: | :---: | :---: | :---: |
| Mode Name | EXI-200AD |  |  |
| Explosion proof structure | Explosion proof | Ex d IIB + $\mathrm{H}_{2}$ T6 IP66 |  |
|  | Dust ignition proof | Ex tD A21 $85{ }^{\circ} \mathrm{C}$ IP66 |  |
| Material container | Aluminum (AL) |  |  |
| Power | AC Type | $100 \mathrm{~V} \sim 240 \mathrm{~V}, 50 / 60 \mathrm{~Hz}$ |  |
|  |  | 110 V | 0.15 A |
|  |  | 220 V | 0.08 A |
|  | DC Type | 12~24 V 1.5 |  |
| Product Size | 218 (W) x 257 (H) x 152 (D) |  |  |
| Temperature Range | $-20{ }^{\circ} \mathrm{C} \sim+40{ }^{\circ} \mathrm{C}$ |  |  |
| Product Weight | Approx. 15 kg |  |  |
| Fuse Capacity | 2 A 250 V |  |  |
| Power Consumption | Approx. 3.9 W |  |  |

### 2.2 Product Labelling



### 2.3 Product Structure and Composition

2.3.1. To form the body, an aluminum composite material suitable for the shaping and usage requirement of the product was selected.
2.3.2. The protective galss is tempered, explosion-proof structure formed by heat treatment and metallic molding to be capable of maintaining sufficient strength.
2.3.3. The wiring connections must be made of metal conduit tubing or a product of equal capacity.
(For all wiring material, only those that have been certified as explosion proof, or a greater safety level or passed the explosion proof efficiency inspection and are still within the certification expirary date are used)
2.3.4. When the product needs to be maintained or repaired after power is supplied to it,

## (1. " Opening is not permitted during when electic currents are applied and before opening the cover the power must be shut off."

### 2.4 Handling Cautions

### 2.4.1 Handling Cautions

(1) If the instrument is dropped or shock is applied to it there is a possibility of a reduction in capability. Therefore handle with care.
(2) If the instrument needs to be opened for installation, inspection, maintenance etc., the power must be cut and caution must be taken not to supply power when it is still open.
(3) When opening or closing the instrument be careful not to cause faults on the connecting surface. When locing the bolts make sure there is no foreign matter on the connecting surface and use tools to completely tighten.
(4) Do not open when applying electric currents

## 3. Features

3.1 Features<br>■ High speed, High accuracy<br>- High speed micro processor adoption<br>- A/D conversion speed: Maximum 200 times/sed<br>- Appropriate for weight and measurement system<br>- Easy operation and various options.<br>- Simple and prompt Full Digital Calibration<br>(SPAC ${ }^{\text {™ }}$ : Single pass automatic span Calibration)<br>- RFI.EMI screened<br>- Watch Dog circuitry (System restoration)<br>- Weight Back-up<br>(Weight memory at sudden power failure)

### 3.2 Main Functions

- Store date, time and calculated data at sudden power failure.
- Various specification on weight conversion speed.
(Digital filter function)
- Various printer connection. (RS-232C Serial printer)
- Tare weight setting with keys.
- Storage of measured times.
- Set Point input \& highest, lowest limit input.
- External input 2 relay.(option)
- External output 4 relay.(option)
- Users can set the desirous max. weight and a division freely.
- Control various external equipment by inner external input/output. (option)
- Print date and time by inner clock.
- Self hardware Test.


### 3.3 Product Specifications

| Power supply |  | Unit |
| :---: | :---: | :---: |
| Power supply voltage | 10~24(DC), 100V~240V(AC) | V |
| Max consumption | 70 with $350 \Omega$ | mA |
| Temperature range |  |  |
| Storage temperature | -25~85 | ${ }^{\circ} \mathrm{C}$ |
| Operating temperature | -20~40 | ${ }^{\circ} \mathrm{C}$ |
| Loadcell |  |  |
| Impedance(complete bridge) | >80 | $\Omega$ |
| Connection | 4 or6 wires |  |
| Loadcell powersupply | $5 \pm 5 \%$ | Vdc |
| Communication |  |  |
| RS485 | Half duplex |  |
| Baud rate | 9600~115200 | BPS |
| Logical inputs |  |  |
| Numbers | 2 |  |
| type | Optocoupler |  |
| Low level voltage | 0~3 | Vdc |
| Higi level voltage | 9~24 | Vdc |
| Current at high level | 10mA@24V | mA |
| Insulation voltage | 2500 | Vms |
| Logical for use metrological characteristics |  |  |
| Class | III or IIII |  |
| Minimum voltage division per verification scale division | 0.5 | uV |
| Maximum voltage for weighing range | 39 | mV |
| Programmable functions |  |  |
| Acquisition of zero, tare, zero tracking |  |  |
| Physical or theoretical calibration |  |  |
| Slope correction |  |  |
| Non-linearity polynomial correction |  |  |


| Low pass, band-stop and self-adaptive digital filters |  |  |
| :---: | :---: | :---: |
| Set points managements |  |  |
| Checkweigher functioning mode |  |  |
| Peak detection functioning mode |  |  |
| Option |  |  |
| Display | 7 Segment LED, 4 key |  |
| A-Out | V-out, l-out | $-10 \mathrm{~V} \sim 10 \mathrm{~V}$ |
| Relay I/O | 2input, 4output |  |
| Alibi memory | 50,000ea Save <br> Real time clock |  |
| Ethernet | 10/100 M |  |

## 4. External Explanation

4.1 External Specifications


218



### 4.2 Frontal Surface Explanation



### 4.2.1 Detailed Explanation

| No. | Name | Function |  |  |
| :---: | :---: | :---: | :---: | :---: |
| (1) | Display | Displays the load weight, status, various messages etc. |  |  |
| (2) | Key (touch key) | Used for function and data input. |  |  |
| (3) | Wiring lead-in tool | Wiring inlet ( 3 openings tota), 2 attachments standard, internal pressure packaging <br> * Use a cable gland which satisfies the KCs explosion proof certification IP66.. |  |  |
|  |  | Standard Inlet | Cable caliber | Joint screw diameter |
|  |  | Left side : for load cell cable | $6 \sim 13.5 \mathrm{~mm}$ | M20*1.5 |
|  |  | Right side : for power cable |  |  |

### 4.2.2 Wiring entrance and ground connection explanation



| $(1)$ | Load cell signal line wiring inlet |
| :--- | :--- |
| $(2)$ | Power line wiring inlet |
| $(3)$ | Wriring inlet for communication line or other optional lines |
| $(4)$ | Gring connector (select based on environment) |

* Ensure wiring is installed in the designated positions as it may affect the capability of the product.


### 4.3 Display Explanantion



| LED | Main function (F5-05 OFF Set) | Sub function (F5-05 ON Set) |
| :---: | :--- | :--- |
| $\circ$ | Stable LED | LED ON : output 4 Closed |
| TARE | Tare LED | LED ON : output 3 Closed |
| NET | On = Net, Off = Gross | LED ON : output 2 Closed |
| $\rightarrow 0 \leftarrow$ | Zero LED | LED ON : output 1 Closed |
| HOLD | Hold LED | LED ON : input 2 Closed |
| COMM | Data CommunicationLED | LED ON : input 1 Closed |
| G | Key OperationLED | Not use |

### 4.4 Key manual

### 4.4.1 EXI-200 KEY PAD



### 4.4.2 Function Key

-Functions of keys used in Normal Mode.

| $\begin{gathered} \text { ZERO } \\ \hline 1 \end{gathered}$ | * Adjust the weight display near the zero-set to 0 . <br> ( $2 \%, 5 \%, 10 \%, 20 \%, 100 \%$ ranges can be selected.) |
| :---: | :---: |
| $\begin{gathered} G / N \\ 2 \end{gathered}$ | *For every press, alternate between totalnet load and display the weight with the lamp indicator. |
| $\begin{gathered} \text { TARE } \\ \hline 3 \\ \hline \end{gathered}$ | * Use the when weighing with the container. <br> * Press the key to save the current weight as the container weight. <br> * To remove the container press the key when the load board is empty. |
| $\begin{gathered} \text { PRINT } \\ \hline 4 \end{gathered}$ | * Press the key to print the currently designated power format. |
| $\frac{1 . S U M}{5}$ | * Use when checking the subtotal value (partial aggregate). |
| $\begin{gathered} \text { G.SUM } \\ 6 \end{gathered}$ | * Use when checking the total value (aggregate). |


| ID 7 | * Use to change the product number. |
| :---: | :---: |
| I.CODE 8 | * Use to input the item code. |
| ITEM | * Use to change the Set Point. |
| $\begin{gathered} \text { HOLD } \\ 0 \end{gathered}$ | * Use when weighing a moving object. |
| $\begin{array}{\|l} \hline \text { CLEAR } \\ \hline \text { CLEAR } \end{array}$ | * Use when deleting all input. |
| MENU <br> ENTER | * Use to enter the menu mode. |
| F1 | * Can be customized to suit the needs. |
| F 2 | * Can be customized to suit the needs. |
| F3 | * Can be customized to suit the needs. |
| F4 | * Can be customized to suit the needs. |

### 4.4.3 Key Lock

-Set the Key Lock Function settings to "use",(F1-23. set 1) and if the Key Lock time setting is set to "10", (F1-24. set 10)
-The front touch key automatically locks if there is no key input for roughly 10 seconds. (If the Key Lock function is activated, the Key status indicator on the display changes to ON)

## menu

- If the ENTER is held down for approximately 2 seconds whilst the Key Lock function is set, the Key Lock function is cancelled.


## 5. Internal Explanation

### 5.1 Internal Explanation.



| No. | Explanation | Notes |
| :---: | :---: | :---: |
| $(1)$ | RS-232 connector(COM1) | Refer to 5.1.3 |
| $(2)$ | RS-232 connector (COM2) | Refer to 5.1.3 |
| (3) | RS-485 connector | Refer to 5.1.3 |
| (4) | RELAY connector | Refer to 5.1.4 |
| (5) | A-OUTconnector |  |
| (6) | Load cell connector | Refer to 5.1.2 |
| (7) | Power connector | Refer to 5.1.1 |

### 5.1.1 Power Connector (AC, DC)

- Before connecting always check the power requirements of the product.
- For fine measurement, measure for $\mathbf{1 0}$ minutes after power is turned on.
(1) AC Type

(2) DC Type



### 5.1.2 Load Cell Connector



EX+ EX- SIG+ SIG- SEN+ SEN- SHD


## Note 1. In case of 4 wires load cell, connect EX+ with SEN+, and connect

 EX- with SEN-Note 2. Max 8 loadcells can connect to EXI-200(when loadcell impeadance $350 \Omega$ )

* Relationship between the load cell output and input sensitivity. The input sensitivity of this product is maximum $0.3 \mathrm{uV} /$ digit or more. The following equation should be satisfied upon the system design.


Example 1) Number of load cell: 4 ea
Rated capacity of load cell: 500 Kg
Rated output of load cell: $2 \mathrm{mV} / \mathrm{V}$
Value of a division: 0.10 Kg
Applied voltage of load cell: $5 \mathrm{~V}(=10,000 \mathrm{mV})$
According to the equation $\rightarrow\left(10000 \mathrm{mV}^{*} 2 \mathrm{mV} * 0.1 \mathrm{Kg}\right) /(500 \mathrm{Kg} * 4)=1 \geq 0.3 \mathrm{uV}$
As the calculated value is greater than 0.3 uV , this weight system design has no problem.

### 5.1.3 RS-232, RS-485 Connector


$\bigcirc \bigcirc \bigcirc$
$\square$ OUT- IN- OUT+ IN+
RS-485

|  | $\bigcirc$ | $O$ |
| :--- | :--- | :--- |
| $\square$ | $\square$ | $\square$ |
| GND | RX | TX |

RS-232(COM2)

|  | $\bigcirc$ | $\bigcirc$ |
| :--- | :--- | :--- |
| $\square$ | $\square$ | $\square$ |
| GND | RX | $\mathbf{T X}$ |

RS-232(COM1)

| Pin <br> Explanation | Connection | Note |
| :---: | :---: | :---: |
| Tx | PC D-SUB No.2 | RS-232 |
| Rx | PC D-SUB No.3 | RS-232 |
| GND | PC D-SUB No.5 | RS-232 |
| IN+ | 485 Converter T+ | RS-485/422 |
| IN- | 485 Converter T- | RS-485/422 |
| OUT + | 485 Converter R + | RS-485/422 |
| OUT- | 485 Converter R- | RS-485/422 |

Reference 1. For the computer RS-422 and RS-485 line PIN numbers, please refer to the PCI card or converter (RS-422) manual.
Reference 2 . The RS- 422 method transfers signals by voltage difference and is more stable in terms of electric noise compared to other methods.
Shield Cable. In addition the wiring should be separated from the AC power cable or electric wiring and for cables communication-specific shield cables ( 0.5 $\phi$ or greater) should be used. The recommended use distance is within 1.2 km .

### 5.1.4 Relay Input(Option)



[^0]
## 6. Weight Calibration Mode

### 6.1 What is weight calibration?

Calibration for adjusting the weight display so the displayed value corresponds with the actual weight.

### 6.2 How to enter the weight calibration mode

To enter the weight calibration mode, open the front of the indicator and turn ON the power when the CAL S/W of the $\mathrm{S} / \mathrm{W}$ depicted in the figure below is ON .

When weight calibration is complete, use after resetting the power.


### 6.3 Weight calibration menu (CAL1 - CAL9)

CAL 1 : Maximum capacity calibration
CAL 2 : Minimum division calibration
CAL 3 : Zero-set and span calibration
CAL 4 : Hopper weight setting
CAL5 : Direct calibration
CAL 6 : Zero adjustment
CAL 7 : Factor calibration
CAL 8 : Gravity adjustment
CAL9 : Setting dual range

### 6.3.1 CAL 1 (Maximum capacity calibration)

| Function: Setting Maximum Value Range of set value: $1 \sim \mathbf{9 9}, 999$ |  |  |
| :---: | :---: | :---: |
| Used key | Display | Descriptions |
|  | $C=10000$ | Max value $=10000 \mathrm{~kg}$ |
| Enter maximum weight | $C=10$ | Max value $=10 \mathrm{~kg}$ |

Reference 1 . The maximum capacity of the weighing scale can measure and display.

### 6.3.2 CAL 2 (Minimum division calibration)

| Function: Minimum division and decimal position setting Range of set value: $\mathbf{0 . 0 0 1 ~ ~ 5 0 ~}$ |  |  |
| :---: | :---: | :---: |
| Used key | Display | Descriptions |
|  | $\mathrm{d}=0.001$ | Minimum division 0.001 kg |
| Enter minimum division | $d=0.01$ | Minimum division 0.01 kg |
| menu Clear | $d=0.1$ | Minimum division 0.1 kg |
|  | $d=\quad 1$ | Minimum division 1 kg |
| Push CLEAR when entering a decimal print |  | Minimum division 10 kg |
| Clear |  |  |
| Reference 1. When clear CLEAR is pressed with decimal point calibrated, 'CAL2' is exited. |  |  |
| Reference 2 . For external exploded view, set within the value of maximum capacity divided by the readability, ' $1 / 30,000$ '. If the external exploded view is greater than ' $1 / 30,000$ ', "Err20" will be displayed. |  |  |
| Reference 3. The decimal point positions is determ | ed as the decimal pos | n of the readability set from 'CAL2'. |

### 6.3.3 CAL 3 (Zero-set and span calibration)

## CAL 3-1

| Function: Setting Multi Calibration Step Range of set value: 1~5 |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
| Used key |  |  | Display | Descriptions |
| Using numeric keys Set the multi step, | HOLD | ITEM <br> 9 | STEP-1 | Setting multi calibration for step 1 (CAL3-3 and CAL 3-4 are carried out once) |
| $\begin{aligned} & \text { Set the multi step, } \\ & \begin{array}{l} \text { MENU } \\ \text { ENTER } \end{array}=\text { Cet, } \text { CLEAR } \\ & \hline \end{aligned}$ | Cancel |  | STEP-5 | Setting multi calibration for step 5 (CAL3-3 and CAL3-4 are carried out five times.) |

* Function used to compensate the load cell power by calibrating multipoints in a particular sector when the actual curve od the load cell is not linear like it is in the figure below.


CAL 3-2

| Function: Zero Calibration |  |  |
| :---: | :---: | :---: |
| Used key | Display | Descriptions |
|  | UnLoAd 1234 - - - | Empty the load tray and press the setup key. <br> The current weight value is displayed. Confirm 'Stable' and press the setup key. <br> Zeroing in progress... |

Reference 1. If the zeroing is completed without any error, it will automatically advance to the counterweight weight setting (CAL3-3) with no need of further input.

## CAL 3-3

| Function: Setting Weight Range of set value: $1 \sim 99,999$ |  |  |
| :---: | :---: | :---: |
| Used key | Display | Descriptions |
| HOLD ITEM | LOAD 1 | It means the weight setting mode. (Number $=$ multi calibration number) |
|  | $W=100.00$ | 100.00 (unit: Kg or Ton) |
|  | $W=0.10$ | 0.10 (unit: Kg or Ton) |

Reference 1 . The counterweight should be set within $10-100 \%$ of the maximum capacity.

CAL 3-4

| Function: Weight Calibration |  |  |
| :---: | :---: | :---: |
| Used key | Display | Descriptions |
|  | $\begin{gathered} \text { LoAd } \\ 12345 \end{gathered}$ | Load the weight set in CAL 4-3 and press the setup key. <br> The current weight value is displayed. Confirm 'Stable' and press the setup key. Span adjustment in progress... |

Reference 1. Repeat 'CAL3-3' and 'CAL3-4' according to the number of STEPs set in 'CAL 3-1'.
At this instance, the weight value must be set to be greater than the previous values.
Reference 2. If the span calibration is completed without any error, "SUCCESS" will be displayed and will advance to the weight verification mode.

Reference 3. If there are no problems after weight verification, pressing

### 6.3.4 CAL4 (Hopper weight setting)

## CAL 4-1

| Function: Setting Multi Calibration Step Range of set value: 2~5 |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
| Used key |  |  | Display | Descriptions |
| Using numeric keys Set the range. | HOLD | $\begin{array}{\|c\|} \hline \text { ITEM } \\ 9 \end{array}$ | STEP-2 | Setting multi calibration for step 2 (for hopper system) |
|  | -Cancel |  | STEP-5 | Setting multi calibration for step 5 (for hopper system) |

CAL 4-2

| Function: Setting Weight Range of set value: 1~99,999 |  |  |  |
| :---: | :---: | :---: | :---: |
| Used key |  |  | Descriptions |
|  | LO | 1 | It means the weight setting mode. (Number $=$ multi calibration number) |
|  | $\mathrm{W}=$ | 0.00 | 100.00 (unit: Kg or Ton) |
|  | $W=$ | 0.10 | 0.10 (unit: Kg or Ton) |

Reference 1 . Set the counterweight within 10 100\% of the maximum capacity.
CAL4-3

| Function: Weight Calibration |  |  |
| :---: | :---: | :---: |
| Used key | Display | Descriptions |
|  | LoAd $12345$ | Load the weight set in CAL 4-3 and press the setup key. <br> The current weight value is displayed. Confirm 'Stable' and press the setup key. Span adjustment in progress... |

Reference 1. Repeat 'CAL4-2', 'CAL4-3' according to the number of STEPs set in 'CAL4-1'.
At this instance the weight value should be calibrated to be greater than the previous values.
Reference 2 . If the span calibration is completed without error, it will advance to CAL-4.

### 6.3.5 CAL 5 (Direct Calibration))

## CAL 5-1

| Function: Direct input about the zero value of loadcell Range of set value: 1~99,999 |  |  |
| :---: | :---: | :---: |
| Used key | Display | Descriptions |
| 0 | ZE-CAL | Direct zero input mode |
| Enter the output value. | 0.0000 | Loadcell zero $=0.0000 \mathrm{mV} / \mathrm{V}$ |
| Emter =Set, Clear =Cancel | 0.1000 | Loadcell zero $=0.1000 \mathrm{mV} / \mathrm{V}$ |

## CAL 5-2

Function: Direct input about the span value of loadcell
Range of set value: 1~99,999

| Used key | Display | Descriptions |
| :---: | :---: | :---: |
| OLD ITEM | SP-CAL | Direct span input mode |
| Using numeric keys Enter the output value. | 1.2000 | Loadcell span $=1.2000 \mathrm{mV} / \mathrm{V}$ |
| Emier =Set, Clear =Cancel | 2.0000 | Loadcell span $=2.0000 \mathrm{mV} / \mathrm{V}$ |

### 6.3.6 CAL 6 (Zero-set adjustment)

| Function: Zero adjustment - calibration when any zeroing error occurs. |  |  |
| :---: | :---: | :--- |
| Used key |  | Display |

Reference 1 . Use when the zeroing is failing due to shock. (Zero-set range is $0 \sim 2 \mathrm{mV} / \mathrm{V}$ )
Reference 2. If zero-set adjustment is completed without error, advance to 'CAL-1'.

### 6.3.7 CAL 7 (Factor Calibration)

| Function: Factor Calibration |  |  |
| :---: | :---: | :---: |
| Used key | Display | Descriptions |
|  | NOTUSE <br> FACtor <br> 12345 | This function cannot be used because of multi calibration. <br> It means you entered the factor correction mode. <br> The current factor is displayed. |

Reference 1. This menu is for weight calibration when counterweight is not available. Regular users will not need to use this.
Reference 2. Can only be used when the multicalibration range of 'CAL3-1' is set to 1.
Reference 3. To enter the FACTOR adjustment mode, PASSWORD must be entered.
6.3.8 CAL 8 (Gravity correction)

| Function: Gravity Adjustment |  |  |
| :---: | :---: | :---: |
| Used key | Display | Descriptions |
|  | $\begin{aligned} & \text { G-CAL } \\ & \text { Gr-CAL } \\ & \text { 9.XXXX } \\ & \text { Gr-SET } \\ & \text { 9.XXXX } \end{aligned}$ | It means you accessed to the menu for the gravity adjustment. <br> Set the gravity for the production place. <br> Set the gravity for the place to use the product. |

Reference 1 . If the gravity between the indicator production location and the location of use is different, gravity can be corrected using this function.

### 6.3.9 CAL 9 (Dual range setting)

## CAL 9-1

| Function: Setting Dual Range Range of set value: $\mathbf{0 \sim 1}$ |  |  |
| :---: | :---: | :---: |
| Used key | Display | Descriptions |
|  | DUAL- 0 | Dual range function is not used. |
|  | DUAL-1 | Dual range function is used. |

Reference 1 . If the resolving power is greater than $1 / 10,000$, "OVER" will be displayed and will return to the CAL menu mode.

CAL 9-2
Function: Setting the applied section for the Dual Range
Range of set value: $0 \sim 99999$

| Used key | Display | Descriptions |
| :---: | :---: | :---: |
|  | M 1000 <br> M 5000 <br> M 10000 | Dual range is applied to less than 1000 kg . <br> Dual range is applied to less than $5,000 \mathrm{~kg}$. <br> Dual range is applied to less than $10,000 \mathrm{~kg}$. |

Reference 1. If the input value is greater than the maximum capacity, "ERR SET" will be displayed and will return to the CAL menu mode.

## 7. Weighing Mode

7.1 Zero-set Function (used when changing the zero-set)

- Zero-set range: within the range set in F1.09

|  | Display Part or Used Keys | Load Plate | Description |
| :---: | :---: | :---: | :---: |
| Step 1 | - 0 | Empty | State with zero changed |
| Step 2 | ZERO |  | Push the zero key |
| Step 3 | $\square 0$ | Empty | State after performing zero function. <br> Namely, the current weight is designated as ${ }^{\prime} 0 \mathrm{~kg}$. |

7.2 Tare function (used when weighing using a container)

■ Maximum tare setting range: maximum capacity

* Caution: The weight value including the container weight cannot exceed the maximum capacity.

|  | Display Part or Used Keys | Load Plate | Description |
| :---: | :---: | :---: | :---: |
| Step 1 | $\because \square 0$ | Tare Placement | State with tare placed on load plate Weight plate : 1.000 kg |
| Step 2 | TARE <br> 3 |  | Push the tare key |
| Step 3 |  | Tare | State with NET lamp turned ON and tare registered |

7.3 Item number changing

|  | Display Part or Used Keys | Load Plate | Description |
| :---: | :---: | :---: | :---: |
| Step 1 | I.CODE 8 |  | Press Item number key. |
| Step 2 | - $0^{-}$ |  | Item Code $=1$ |
| Step 2 | HOL ITEM <br> 0 9 |  | Change the item number. |
| Step 3 | Menu |  | Item number is saved |

7.4 Set point changing

|  | Display Part or Used Keys | Load Plate | Description |
| :---: | :---: | :---: | :---: |
| Step 1 | ITEM <br> 9 |  | Press the Item key |
| Step 2 |  |  | Displayed current setpoint number. |
| Step 2 |  |  | Change the set point value |
| Step 3 | $\begin{aligned} & \text { MENU } \\ & \text { ENTER } \end{aligned}$ |  | Set point is saved |
| Step 4 |  |  | Repeat setpl~3 until end point of max set point |

### 7.5 Subtotal Print

The product number of the steel reinforcement is assumed to be ' 10 '.

|  | Display Part or Used Keys |  |  |  | Load Plate | Description |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Step 1 | $1.000 E$ <br> 8 | ZERO 1 | HOLD | MENU |  | Select the item number code as ' 10 ' |
| Step 2 |  | 1.5UM <br> 5 |  |  |  | Push No.5(Subtotal) key "No. 5 key pushed" is displayed in the message window |
| Step 3 |  | PRINT |  |  |  | The subtotal value of item No. 10 is printed in the designated form. |

Reference 1 . The print format is designated as below.

| SUB-TOTAL |  |
| :---: | :---: |
| DATE | 2012/ 1/1 |
| TIME | 09:30 |
| ID | 1 |
| COUNT | 5 |
| TOTAL | 350.0 kg |

Reference 2 . The subtotal DATA is automactically or manually deleted based on the menu number[F7-03].

### 7.6 Total Print

| Step 1 | Display Part or Used Keys | Load Plate | Description |
| :---: | :---: | :---: | :--- |
| Step 2 | 6.SUM <br> 6 | Push No.5(Total)key <br> "No.5 key pushed" is <br> displayed in the message <br> window |  |
|  | PRINT | Sum of all subtotal <br> information itemNos.0-99 <br> isprinted as inthe designated <br> form. |  |

Reference 1 . The print format is designated as below.

| GRAND-TOTAL |  |
| :---: | :---: |
| DATE | 2012/ 1/2 |
| TIME | 10:30 |
| ID | 10 |
| COUNT | 123 |
| TOTAL | 12350.0 kg |

Reference 2 . The subtotal DATA is automactically or manually deleted based on the menu number[F7-03].

## 8. Test Mode

How to enter test mode


1: Key Test
2 : Display Test
3 : AD Test
4 : Communication Test
5 : External Input/output Test(OPTION)
6:A-OUT Test(OPTION)
$7: 1 / 10$ division Test
8 : EEPROM Test
9 : RTC Test (OPTION)

### 8.1 TEST 1 (Key Test)

| Function: Key test |  | Display |
| :---: | :---: | :---: |

< Key List>

| Key | No | Code | Key | No | Code | Key | No | Code |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| ZERO <br> $\mathbf{1}$ | 1 | 1 | ID <br> $\mathbf{7}$ | 7 | 7 | F3 | F3 | 30 |
| G/N <br> $\mathbf{2}$ | 2 | 2 | I.CODE <br> $\mathbf{8}$ | 8 | 8 | F4 | F4 | 31 |
| TARE <br> $\mathbf{3}$ | 3 | 3 | ITEM <br> $\mathbf{9}$ | 9 | 9 | CLEAR <br> CLEAR | CLEAR | 27 |
| PRINT <br> $\mathbf{4}$ | 4 | 4 | HOLD <br> $\mathbf{0}$ | 0 | 0 | MENU <br> ENTER | ENTER | 30 |
| I.SUM <br> $\mathbf{5}$ | 5 | 5 | F1 | F1 | 28 |  |  |  |
| G.SUM <br> $\mathbf{6}$ | 6 | 6 | F2 | F2 | 29 |  |  |  |

### 8.2 TEST 2 (Display Test)

Function: Display Screen Test

| Used key | Display | Descriptions |
| :---: | :---: | :---: |
|  |  | All LED lamp is on. |

### 8.3 TEST 3 (AD Test)



### 8.4 TEST 4 (Communication Test)

| Function: Serial Communication Test |  |  |
| :--- | :---: | :--- |
| Used key | Display | Descriptions |
| MENU | TX--RX | Status to wait for transmission or <br> reception <br> ENTER : Next Menu |
| Otherkeys:Test | ------ | Transmission: 2, Reception: 13 |

Reference 1. Run this test while the communication program in the computer
(ex: Hyper Terminal) is executing after connecting a serial port in the computer to the serial port on the back.
Reference 2 . Send ' 1 ' from the computer keyboard, check whether or not ' 1 ' is received properly on the indicator's screen, and then check whether or not ' 1 ' is received properly on the computer after pressing ' 1 ' from the indicator's keyboard.

### 8.5 TEST 5 (External Input/output Test_OPTION)

| Function : External Input / Output Test |  |  |
| :---: | :---: | :---: |
| Used key | Display | Descriptions |
|  | $\begin{gathered} 1-X 0-X \\ --------1 \\ 1-20-4 \end{gathered}$ | Displayed in the external input section when there is an external input. <br> Push $\triangle$ key to execute weighing external output <br> input: 2 , output: 4 |

Reference 1. This test operates only if Ext IO Option Card is mounted

### 8.6 TEST 6 (A-OUT Test _OPTION)

| Function : A-Out Test |  |  |
| :---: | :---: | :---: |
| Used key | Display | Descriptions |
| MENU <br> ENTER : NextMenu <br> Otherkeys:Test | $25 \quad$ P | The output level of Aout is raised by $25 \%$ each <br> time the $\Delta$ key is pushed. |

Reference 1. This test operates only if Analog out Option Card is mounted.

### 8.7 TEST 7 (1/10 division Test)

Function: 1/10 division Test

| Used key | Display | Descriptions |
| :---: | :---: | :---: |
|  | XXXXXX | Display as $1 / 10$ weighing scale units. |

### 8.8 TEST 8 (EEPROM Test)

Function: EEPROM Test

| Used key | Display | Descriptions |
| :---: | :---: | :---: |
| MENU | ROM OK |  |
| ENTER : NextMenu | ROM NG | Display EEPROM status |

### 8.9 TEST 9 (RTC Test_OPTION)

| Function: RTC Test |  |  |
| :---: | :---: | :---: |
| Used key | Display | Descriptions |
| MENU <br> ENTER :NextMenu | SEC XX | XX : Displaying the progress of <br> seconds (SEC) |

Reference 1 . This test only functions if the (subtotal)RTC option card is installed.
Reference 2. Press $\begin{gathered}\text { Clear } \\ \text { clear } \\ \\ \end{gathered}$

## 9. Set Mode

### 9.1 How to enter set mode



After testing in set mode, press
ClEAR

| Classification | Menu | SubMenu |
| :---: | :---: | :---: |
| 1. General Setting | F1.01 | Set AD speed |
|  | F1.02 | Set average filter |
|  | F1.03 | Set Low Pass Filter |
|  | F1.04 | Set Band Stop Filter |
|  | F1.05 | Not use |
|  | F1.06 | Set stable range |
|  | F1.07 | Set Automatic Zero <br> Tracking Compensation |
|  | F1.08 | Set Weight Back-up |
|  | F1.09 | Set Zero range |
|  | F1.10 | Set Tare range |
|  | F1.11 | Set Init Zero |
|  | F1.12 | Set Weighing Unit |
|  | F1.13 | Set F1 Key Use Type |
|  | F1.14 | Set F2 Key Use Type |
|  | F1.15 | Set F3 Key Use Type |
|  | F1.16 | Set F4 Key Use Type |
|  | F1.17 | Set Hold Type |
|  | F1.18 | Set Average Hold time |
|  | F1.19 | Set Hold Canceling Conditions |
|  | F1.20 | Set Automatic Hold Starting Conditions |
|  | F1.21 | Set Automatic Hold Canceling Conditions |
|  | F1.22 | Set Key Operating Conditions |
|  | F1.23 | Set use Key Lock |
|  | F1.24 | Set Key Lock time |
|  | F1.25 | Initializing of set values |
|  | F1.26 | Set Key Sensitivity |


| Classification | Menu | SubMenu |
| :---: | :---: | :---: |
| 2. Communication Setting | F2.01 | Set Device ID |
|  | F2.02 | Set Data Transmission Rate |
|  | F2.03 | Set COM1 Port Setting |
|  | F2.04 | Set COM1 Baud Rate |
|  | F2.05 | Set COM1 Out Data |
|  | F2.06 | Set COM1 Output Format |
|  | F2.07 | Set COM1 Output mode |
|  | F2.08 | Set COM2 Port Setting |
|  | F2.09 | Set COM2 Baud Rate |
|  | F2.10 | Set COM2 Out Data |
|  | F2.11 | Set COM2 Output Format |
|  | F2.12 | Set COM2 Output mode |
|  | F2.13 | Set RS-422/485 Port Setting |
|  | F2.14 | Set RS-422/485 Baud Rate |
|  | F2.15 | Set RS-422/485 Out Data |
|  | F2.16 | Set RS-422/485 Output Format |
|  | F2.17 | Set RS-422/485 Output mode |


| Classification | Menu | SubMenu |
| :--- | :--- | :--- |
| 3. A-Out Setting | F3.01 | A-out Range |
|  | F3.02 | V-out Range |
|  | F3.03 | I-out Range |
|  | F3.04 | Dual output mode |
|  | F3.05 | Minimum weight of A-out |
|  | F3.06 | Maximum weight of A-out |
|  | F3.07 | Adjust zero of A-out |
|  | F3.08 | Adjust span of A-out |


| Classification | Menu | SubMenu |
| :--- | :--- | :--- |
| 4. Device Setting | F4.01 | Set Date |
|  | F4.02 | Set Time |
|  | F4.03 | Use Alibi memory |
|  | F4.04 | Memory over writing |


| Classification | Menu | SubMenu |
| :--- | :--- | :--- |
| 5. Relay Setting | F5.01 | Relay Out mode |
|  | F5.02 | Ext input 1 |
|  | F5.03 | Ext input 2 |
|  | F5.04 | Relay Reverse On/Off |
|  | F5.05 | Relay Display |


| Classification | Menu | SubMenu |
| :--- | :--- | :--- |
| 6. TCP.IP | F6.01 | Set DHCP |
|  | F6.02 | Set Server /Client |
|  | F6.03 | EXI-200's IP Server mode |
|  | F6.04 | Subnet Mask |
|  | F6.05 | Gate way |
|  | F6.06 | EXI200's TCP Port Server mode |
|  | F6.07 | Comm type of Server mode |
|  | F6.08 | Set Client IP |
|  | F6.09 | Set Client's TCP Port |
|  | F6.10 | Comm type of Client mode |


| Classification | Menu | SubMenu |
| :--- | :--- | :--- |
| 7. Print Function | F7.01 | Print Type |
|  | F7.02 | Print Form |
|  | F7.03 | Manage Print Data |
|  | F7.04 | Print Line Feed |
|  | F7.05 | Print Head Message |
|  | F7.06 | Print Delay Time |
|  | F7.07 | Print Condition |
|  | F7.08 | Print Set Automatic |
|  | F7.09 | Print Count Number |

### 9.2 General Function

Menu-F1.01: Set AD Speed

| Function | AD Speed Setting |  |  |
| :---: | :---: | :---: | :---: |
| Set Range (0-8) | Display Part |  | Meaning |
|  | 1-01. | 0 | Converting speed 5 times per second |
|  | $1-01$. | 1 | Converting speed 10 times per second |
|  | 1-01. | 2 | Converting speed 20 times per second |
|  | 1-01. | 3 | Converting speed 40 times per second |
|  | 1-01. | 4 | Converting speed 100 times per second |
|  | 1-01. | 5 | Converting speed 160 times per second |
|  | 1-01. | 6 | Converting speed 320 times per second |
|  | 1-01. | 7 | Converting speed 800 times per second |
|  | 1-01. | 8 | Converting speed 1600 times per second |

Reference 1. After changing the AD speed, press
to display the weight using the altered value.
MENU
(Press ENTER after checking the changed value to return to the previous mode)

Menu-F1.02: Set average filter

| Function | Average filter Setting |  |
| :---: | :---: | :--- |
| Set Range <br> $(1 \sim 50)$ | Display Part | $1-02: \mathrm{XX}$ <br> Initial Value $: \mathbf{1 0}$ |
|  | Setting the number of buffers in the average filter |  |

Reference 1 . Set based on the environment. (The rate of change of weight may slow)

## Menu-F1.03: Set Low Pass Filter

| Function | Low Pass Filter Setting |  |
| :---: | :---: | :--- |
|  | Display Part |  |
| Set Range <br> $(0 \sim 1)$ | $1-03:$ XX <br> Initial Value: $\mathbf{0}$ | Low Pass Filter use setting.(0: Not use, 1:Use) |
| Set Range <br> $(2 \sim 4)$ | F-od.XX <br> Initial Value: $\mathbf{2}$ | Low Pass Filter Degree setting. |
| Set Range <br> $(1 \sim 1600)$ | C-FrEq <br> Initial Value : $\mathbf{1 0}$ | Low Pass Filter Frequency setting |

Reference 1. Uses the LPF (Low Pass Filter). The LPF order and LPF frequency setting menus are only displayed in this mode.
Reference 2. When using LPF, set according to the environment.

## Menu-F1.04: Set Band Stop Filter

| Function | Band Stop Filter Setting |  |
| :---: | :---: | :--- |
|  | Display Part | Meaning |
| Set Range <br> $(0 \sim 1)$ | $1-04: X X$ <br> Initial Value :0 | Band Stop Filter use setting.(0: Not use, 1: Use) |
| Set Range <br> $(1 \sim 1600)$ | H-FrEq <br> Initial Value : $\mathbf{6 0}$ | Band Stop Filter High Frequency setting. |
| Set Range <br> $(1 \sim 1600)$ | L-FrEq <br> Initial Value $: \mathbf{1 0}$ | Band Stop Filter Low Frequency setting. |

Reference 1.Uses BSP (Band Stop Filter). The BSP High Frequency, BSP Low Frequency setting menus are only displayed in this mode.
Reference 2. When using BSP, set according to the environment.

Menu-F1.06: Set Stable Weight Range

| Function | Stable Weight Range Setting |  |
| :---: | :---: | :--- |
| Set Range <br> $(0 \sim 99)$ | Display Part | Meaning |
|  | Initial Value : <br> $\mathbf{1 x ~ 0 . 5 ~ d i v i s i o n ~}$ | Stability lamp is turned ON when weight change is such that the width <br> of change in a given time is within the set value x 0.5 division |

Reference 1. This function verifies the stable status when the weight fluctuation does not exceed $0.5 x$ the readability setting within the set time.
Reference 2. The number should be made large and small for high-vibration and low-vibration environments respectively to quickly stabilize the weighing status.

## Menu-F1.07: Set Automatic Zero-set Range

| Function | Automatic Zero-set Range Setting |  |
| :---: | :---: | :--- |
| Set Range <br> $(0 \sim 99)$ | Display Part <br> Initial Value: <br> $\mathbf{1 x ~ 0 . 5 ~ d i v i s i o n ~}$ | Stability lamp is turned ON when weight change is such that the <br> width of change in a given time is within the set value 0.5 <br> division |
|  | deang |  |

Reference 1. This function automatically corrects the zero-set if the weight does not exceed a set readability range within a set time when at zero-set state.
Ex) If the MENU [F1-07] is set to " 2 " when the maximum labeled increment is 120.0 kg and the value of a single increment is 0.05 kg


Menu-F1.08: Set Weight Back-up

| Function | Weight Back-up Setting |  |
| :---: | :---: | :---: |
| Set Range$(0,1)$ | Display Part | Meaning |
|  | 1-08. 0 | Weight back up function is not used |
|  | 1-08. 1 | Weight back up is used (based on operation) |

Menu-F1.09: Set Zero Key Range

| Function | Zero Key Range Setting |  |
| :---: | :---: | :--- |
| Set Range <br> $(0-99)$ | Display Part | Meaning |
|  | I-09. XX |  |
|  | Initial Value: | Zero operates up to within $+/$ - OO\% of the maximum weight |
|  | $\mathbf{1 0 \%}$ |  |

## Menu-F1.10: Set Tare Key Range

| Function | Tare Key Range Setting |  |
| :---: | :---: | :--- |
| Set Range <br> $(0 \sim 100)$ | Display Part | Meaning |
|  | I-10.XX |  |
|  | Initial Value: <br> $\mathbf{1 0 0 \%}$ | Tare operates up to within $+/-00 \%$ of the maximum weight |

## Menu-F1.11: Set Initial Zero Range

| Function | Initial Zero Range Setting |  |
| :---: | :---: | :--- |
| Set Range <br> $(0-99)$ | Display Part | Meaning |
|  | $1-11 . \mathrm{XX}$ | Initial Value: |
|  | $\mathbf{1 0 \%}$ | Initial zero operates within $+/-00 \%$ of the Gross Weight |

Menu-F1.12: Set Overload Range

| Function | Overload Range Setting |  |
| :---: | :---: | :--- |
| Set Range | Display Part | Meaning |
|  | 1-12. XX |  |
|  | Initial Value : | Overweight from the next to 0 $\times 1$ Digit of the maximum weight |
|  | 9x1 Digit |  |

Menu-F1.13: Set F1 Key Use Type

| Function | F1 Key Use Type Setting |  |
| :---: | :---: | :--- |
| Set Range <br> $(0 \sim 8)$ | Display Part | Meaning |
|  | $\mathbf{1 - 1 3 . 0 0}$ | F1 Key used as the tare/tare cancelling key |
|  | $1-13.01$ | F1 Key used as the total/net weight key |
|  | $1-13.02$ | F1 Key used as the Hold key |
|  | $1-13.03$ | F1 Key used as the Holdless key |
|  | $1-13.04$ | F1 Key used as the Tare key |
|  | $1-13.05$ | F1 Key used as the Cleaning key |
|  | $1-13.06$ | F1 Key used as the Tare cancelling key |
|  | $1-13.07$ | F1 Key used as the Set Point 1 key |
|  | $1-13.08$ | F1 Key used as the Set Point 2 key |

Menu-F1.14: Set F2 Key Use Type

| Function | F2 Key Use Type Setting |  |
| :---: | :---: | :--- |
| Set Range <br> $(0 \sim 8)$ | Display Part | Meaning |
|  | $1-14.00$ | F2 Key used as the tare/tare cancelling key |
|  | $\mathbf{1 - 1 4 . 0 1}$ | F2 Key used as the total/net weight key |
|  | $1-14.02$ | F2 Key used as the Hold key |
|  | $1-14.03$ | F2 Key used as the Holdless key |
|  | $1-14.04$ | F2 Key used as the Tare key |
|  | $1-14.05$ | F2 Key used as the Cleaning key |
|  | $1-14.06$ | F2 Key used as the Tare cancelling key |
|  | $1-14.07$ | F2 Key used as the Set Point 1 key |
|  | $1-14.08$ | F2 Key used as the Set Point 2 key |

Menu-F1.15: Set F3 Key Use Type

| Function | F3 Key Use Type Setting |  |
| :---: | :---: | :--- |
| Set Range <br> $(0 \sim 8)$ | Display Part |  |
|  | $1-15.00$ | F3 Key used as the tare/tare cancelling key |
|  | $1-15.01$ | F3 Key used as the total/net weight key |
|  | $\mathbf{1 - 1 5 . 0 2}$ | F3 Key used as the Hold key |
|  | $1-15.03$ | F3 Key used as the Holdless key |
|  | $1-15.04$ | F3 Key used as the Tare key |
|  | $1-15.05$ | F3 Key used as the Cleaning key |
|  | $1-15.06$ | F3 Key used as the Tare cancelling key |
|  | $1-15.07$ | F3 Key used as the Set Point 1 key |
|  | $1-15.08$ | F3 Key used as the Set Point 2 key |

Menu-F1.16: Set F4 Key Use Type

| Function | F4 Key Use Type Setting |  |
| :---: | :---: | :--- |
| Set Range <br> $(0 \sim 8)$ | Display Part | Meaning |
|  | $1-16.00$ | F4 Key used as the tare/tare cancelling key |
|  | $1-16.01$ | F4 Key used as the total/net weight key |
|  | $1-16.02$ | F4 Key used as the Hold key |
|  | $\mathbf{1 - 1 6 . 0 3}$ | F4 Key used as the Holdless key |
|  | $1-16.04$ | F4 Key used as the Tare key |
|  | $1-16.05$ | F4 Key used as the Cleaning key |
|  | $1-16.06$ | F4 Key used as the Tare cancelling key |
|  | $1-16.07$ | F4 Key used as the Set Point 1 key |

Menu-F1.17: Set Hold Type

| Function | Hold Type Setting |  |  | Meaning |  |
| :---: | :---: | :--- | :---: | :---: | :---: |
| Set Range | Display Part |  |  |  |  |
|  | $1-17.00$ | Average Value Hold |  |  |  |
|  | $1-17.01$ | Peak Hold |  |  |  |
|  | $1-17.02$ | Sampling Hold |  |  |  |
|  | $1-17.03$ | Automatic Hold |  |  |  |

## Menu-F1.18: Set Average hold time

| Function | Average hold time Setting |  |
| :---: | :---: | :---: |
| Set Range <br> $(00 \sim 99)$ | Display Part | Meaning |
|  | $1-18 . \mathrm{XX}$ <br> Initial Value $: 30$ | Average value within the set value x sec is calculated |

Menu-F1.19: Set Hold Canceling Conditions

| Function | Hold Canceling Conditions Setting |  |
| :---: | :---: | :--- |
| Set Range <br> (0-2) | Display Part | Meaning |
|  | $\mathbf{1 - 1 9 . 0 0}$ | Hold is canceled when it becomes zero |
|  | $1-19.01$ | Hold is canceled when Hold key is entered |
|  | $1-19.02$ | Hold is canceled when Hold less key entered |

Menu-F1.20: Set Automatic Hold Starting Conditions

| Function | Automatic Hold Starting Conditions Setting |  |
| :---: | :---: | :--- |
| Set Range <br> $(2-99)$ | Display Part | Meaning |
|  | $1-20 . \mathrm{XX}$ <br> Initial Value $: 10$ | Hold Starts when the weight changes within the set <br> range value x 1 division |

Menu-F1.21: Set Automatic Hold Canceling Conditions

| Function | Automatic Hold Canceling Conditions Setting |  |
| :---: | :---: | :--- |
| Set Range <br> $(00 \sim 99)$ | Display Part <br> Initial Value $: \mathbf{1 0}$ | Hold is canceled when the value is changed by more <br> Than $00 \%$ of the hold value |
|  |  |  |

Menu-F1.22: Set Key Operating Conditions

| Function | Key Operating Conditions(Zero, Tare) Setting |  |  |
| :---: | :---: | :--- | :---: |
| Set Range <br> $(0,1)$ | Display Part | Meaning |  |
|  | $1-22.0$ | Always in operation |  |
|  | $\mathbf{1 - 2 2 . 1}$ | Operates only if the weight is stable |  |

Menu-F1.23: Set use Key Lock

| Function | Key Lock use Setting |  |  |
| :---: | :---: | :--- | :--- |
| Set Range | Display Part |  | Meaning |
|  | $\mathbf{1 - 2 3 . 0}$ | Unlock front key |  |
|  | $1-23.1$ | Lock front key |  |

## Menu-F1.24: Set Key Lock time

| Function | Key Lock Time Setting |  |
| :---: | :---: | :---: |
| Set Range <br> $(0-99)$ | Display Part | Meaning |
|  | $1-24 . ~ X X$ <br> Initial Value $: 10$ | Lock front key when setting value x 1 seconds exceeded |

Reference 1. Can be used when the F1.23 Use Key Lock Setting is set to 1.

## Menu-F1.25: Initializing of set values

| Function | Initializing of set values |  |
| :---: | :---: | :--- |
| Set Range <br> $(0,1)$ | Display Part | Meaning |
|  | $\mathbf{1 - 2 5 . 0}$ | No set values of the product are initialized to factory shipping state |
|  | $1-25.1$ | All set values of the product are initialized to factory shipping state |

## Menu-F1.26: Set Key Sensitivity

| Function | Set Key Sensitivity |  |
| :---: | :---: | :--- |
| Set Range | Display Part | Meaning |
|  | $1-26.0$ | Key sensitivity is very low. |
|  | $1-26.1$ | Key sensitivity is low. |
|  | $\mathbf{1 - 2 6 . 2}$ | Key sensitivity is high. |
|  | $1-26.3$ | Key sensitivity is very high. |

[^1]
### 9.3 Communication Setting

Menu-F2.01: Equipment Number

| Function | Equipment Number |  |
| :---: | :---: | :---: |
| Set Range <br> $(0 \sim 99)$ | Display Part | Meaning |
|  | 2-01.XX <br> Initial Value $: \mathbf{0}$ | Desired device ID may be entered. |

Reference 1 . This function can be used as the indicator unique ID when using COMMAND mode.

## Menu-F2.02: Data Transfer Speed Setting

| Function | Data Transfer Speed Setting |  |
| :---: | :---: | :---: |
| Set Range$(0 \sim 9999)$ | Display Part | Meaning |
|  | XXXX Initial Value: 50x10ms | Data are transmitted by the unit of $00 \times 10 \mathrm{~ms}$ |

Reference 1 . When set to " 0 ", data is transferred in real-time.

## Menu-F2.03: Set COM1 Port

| Function | Com1 RS-232C Port Setting |  |
| :---: | :---: | :---: |
| Set Range$(0,5)$ | Display Part | Meaning |
|  | 2-03. 0 | Data Bit 8, Stop Bit 1, Parity Bit : None |
|  | 2-03. 1 | Data Bit 7, Stop Bit 1, Parity Bit: Even |
|  | 2-03. 2 | Data Bit 7, Stop Bit 1, Parity Bit: Odd |
|  | 2-03. 3 | Data Bit 7, Stop Bit 2, Parity Bit: Odd |
|  | 2-03. 4 | Data Bit 8, Stop Bit 1, Parity Bit: Even |
|  | 2-03. 5 | Data Bit 8, Stop Bit 1, Parity Bit: Odd |

## Menu-F2.04: Set COM1 Baud Rate

| Function | COM1 RS-232C Baud Rate Setting |  |
| :---: | :---: | :---: |
| Set Range$(0 \sim 7)$ | Display Part | Meaning |
|  | 2-04. 0 | 1,200 bps |
|  | 2-04. 1 | 2,400 bps |
|  | 2-04. 2 | 4,800 bps |
|  | 2-04. 3 | 9,600 bps |
|  | 2-04. 4 | 19,200 bps |
|  | 2-04. 5 | 38,400 bps |
|  | 2-04. 6 | 57,600 bps |
|  | 2-04. 7 | 115,200 bps |

## Menu-F2.05: Set COM1 Out Data

| Function | COM1 RS-232C Out Data Setting |  |
| :---: | :---: | :--- |
| Set Range | Display Part | Meaning |
|  | $\mathbf{2 - 0 5 .} \mathbf{0}$ | Displayed value is transmitted |
|  | $2-05.1$ | Gross Weight is transmitted |
|  | $2-05.2$ | Net weight is transmitted |

Menu-F2.06: COM1 Output Format

| Function | COM1 RS-232C Output Format |  |
| :---: | :---: | :--- |
| Set Range <br> $(0 \sim 3)$ | Display Part | Meaning |
|  | 2-06. 0 | 22 byte ofCAS |
|  | $2-06$. | 1 |
|  | 2-06. 2 | 10 byte ofCAS |
|  | $2-06$. | 3 |

Reference 1. Refer to $<$ Appendix $1>$ for the communication format
Menu-F2.07: COM1 Communication Method

| Function | COM1 Communication Method (RS-232C-Output mode) |  |
| :---: | :---: | :--- |
| Set Range <br> $(0 \sim 8)$ | Display Part | Meaning |
|  | 2-07. 0 | Data is not transmitted |
|  | $2-07.1$ | Transmitted only if the print key is pushed |
|  | $2-07.2$ | Transmitted in both stable/unstable cases <br> (Stream Mode) |
|  | $2-07.3$ | Transmitted only if the weight is stable |
|  | $2-07.4$ | Command Type 1 |
|  | $2-07.5$ | Command Type 2 |
|  | $2-07.6$ | Command Type 3 |
|  | $2-07.7$ | Transmitted only upon completion signal |
|  | $2-07.8$ | Modbus protocol |

Reference 1. Refer to Appendix 2, 3 and 4 for command types.

## Menu-F2.08: Set COM2 Port

| Function | COM2 RS-232C Port Setting |  |
| :---: | :---: | :--- |
| Set Range <br> $(0 \sim 5)$ | Display Part | Meaning |
|  | 2-03. 0 | Data Bit 8, Stop Bit 1, Parity Bit: None |
|  | 2-03. 1 | Data Bit 7, Stop Bit 1, Parity Bit: Even |
|  | 2-03. 2 | Data Bit 7, Stop Bit 1, Parity Bit: Odd |
|  | $2-03.3$ | Data Bit 7, Stop Bit 2, Parity Bit: Odd |
|  | 2-03. 4 | Data Bit 8, Stop Bit 1, Parity Bit: Even |
|  | $2-03.5$ | Data Bit 8, Stop Bit 1, Parity Bit: Odd |

Menu-F2.09: Set COM2 Baud Rate

| Function | COM2 RS-232C Baud Rate Setting |  |
| :---: | :---: | :--- |
| Set Range <br> $(0 \sim 7)$ | Display Part | Meaning |
|  | $2-09.0$ | $1,200 \mathrm{bps}$ |
|  | $2-09.1$ | $2,400 \mathrm{bps}$ |
|  | $2-09.2$ | $4,800 \mathrm{bps}$ |
|  | $\mathbf{2 - 0 9 .} \mathbf{3}$ | $9,600 \mathrm{bps}$ |
|  | $2-09.4$ | $19,200 \mathrm{bps}$ |
|  | $2-09.5$ | $38,400 \mathrm{bps}$ |
|  | $2-09.6$ | $57,600 \mathrm{bps}$ |

Menu-F2.10: Set COM2 Out Data

| Function | COM2 RS-232C Out Data Setting |  |
| :---: | :---: | :--- |
| Set Range <br> $(0 \sim 2)$ | Display Part | Meaning |
|  | $\mathbf{2 - 1 0 .} \mathbf{0}$ | Displayed value is transmitted |
|  | $2-10.1$ | Gross Weight is transmitted |
|  | $2-10.2$ | Net weight is transmitted |

Menu-F2.11: COM2 Output Format

| Function | COM2 RS-232C Output Format |  |
| :---: | :---: | :--- |
| Set Range | Display Part | Meaning |
|  | $\mathbf{2 - 1 1 . 0}$ | 22 byte ofCAS |
|  | $2-11.1$ | 10 byte ofCAS |
|  | $2-11.2$ | 18 byte Format(AND, FINE) |
|  | $2-11.3$ | 22 byte ofCAS with relay status |

Reference 1. Refer to <Appendix $1>$ for the communication format
Menu-F2.12: COM2 Communication Method

| Function | COM2 Communication Method (RS-232C-Output mode) |  |
| :---: | :---: | :---: |
| Set Range$(0 \sim 8)$ | Display Part | Meaning |
|  | 2-12. 0 | Data is not transmitted |
|  | 2-12. 1 | Transmitted only if the print key is pushed |
|  | 2-12. 2 | Transmitted in both stable/unstable cases (Stream Mode) |
|  | 2-12. 3 | Transmitted only if the weight is stable |
|  | 2-12. 4 | Command Type 1 |
|  | 2-12. 5 | Command Type 2 |
|  | 2-12. 6 | Command Type 3 |
|  | 2-12. 7 | Transmitted only upon completion signal |
|  | 2-12. 8 | Modbus protocol |

Reference 1. Refer to Appendix 2, 3 and 4 for command types.

Menu-F2.13: Set RS-422/485 Port

| Function | RS-422/485 Port Setting |  |
| :---: | :---: | :---: |
| Set Range$(0 \sim 5)$ | Display Part | Meaning |
|  | 2-13. 0 | Data Bit 8, Stop Bit 1, Parity Bit : None |
|  | 2-13. 1 | Data Bit 7, Stop Bit 1, Parity Bit: Even |
|  | 2-13. 2 | Data Bit 7, Stop Bit 1, Parity Bit: Odd |
|  | 2-13. 3 | Data Bit 7, Stop Bit 2, Parity Bit: Odd |
|  | 2-13. 4 | Data Bit 8, Stop Bit 1, Parity Bit: Even |
|  | 2-13. 5 | Data Bit 8, Stop Bit 1, Parity Bit: Odd |

Menu-F2.14: Set RS-422/485 Baud Rate

| Function | RS-422/485 Baud Rate Setting |  |
| :---: | :---: | :---: |
| Set Range$(0 \sim 7)$ | Display Part | Meaning |
|  | 2-14. 0 | 1,200 bps |
|  | 2-14. 1 | 2,400 bps |
|  | 2-14. 2 | 4,800 bps |
|  | 2-14. 3 | 9,600 bps |
|  | 2-14. 4 | 19,200 bps |
|  | 2-14. 5 | 38,400 bps |
|  | 2-14. 6 | 57,600 bps |
|  | 2-14. 7 | 115,200 bps |

Menu-F2.15: Set RS-422/485 Out Data

| Function | RS-422/485 Out Data Setting |  |
| :---: | :---: | :--- |
| Set Range <br> $(0 \sim 2)$ | Display Part |  |
|  | $\mathbf{2 - 1 5 . 0}$ | Displayed value is transmitted |
|  | $2-15.1$ | Gross Weight is transmitted |
|  | $2-15.2$ | Net weight is transmitted |

Menu-F2.16: RS-422/485 Output Format

| Function | RS-422/485 Output Format |  |
| :---: | :---: | :--- |
|  | Display Part | Meaning |
| Set Range | $\mathbf{2 - 1 6 .} \mathbf{0}$ | 22 byte ofCAS |
| $(0 \sim 3)$ | $2-16.1$ | 10 byte ofCAS |
|  | $2-16.2$ | 18 byte Format(AND,FINE) |
|  | $2-16 . ~$ | 2 |

Reference 1. Refer to <Appendix $1>$ for the communication format

Menu-F2.17: RS-422/485 Communication Method

| Function | RS-422/485 Communication Method (Output mode) |  |
| :---: | :---: | :---: |
| Set Range(0~8) | Display Part | Meaning |
|  | 2-17. 0 | Data is not transmitted |
|  | 2-17. 1 | Transmitted only if the print key is pushed |
|  | 2-17. 2 | Transmitted in both stable/unstable cases (Stream Mode) |
|  | 2-17. 3 | Transmitted only if the weight is stable |
|  | 2-17. 4 | Command Type 1 |
|  | 2-17. 5 | Command Type 2 |
|  | 2-17. 6 | Command Type 3 |
|  | 2-17. 7 | Transmitted only upon completion signal |
|  | 2-17. 8 | Modbus protocol |

Reference 1. Refer to Appendix 2, 3 and 4 for command types.

### 9.4 Analogue Output Setting

Menu-F3.01: A-out activation range setting

| Function | Set A-Out range |  |
| :---: | :---: | :--- |
| Set Range <br> $(0,1)$ | Display Part | Meaning |
|  | 3-01. 0 | Unipolar(operating in + weight) |
|  | $3-01.1$ | Bipolar(operating in $\pm$ weight) |

Menu-F3.02: V-out range setting

| Function | V-out range |  |
| :---: | :---: | :--- |
| Set Range <br> (0~4) | Display Part | Meaning |
|  | $3-02 . \quad 0$ | V-out is closed |
|  | $3-02.1$ | $0 \mathrm{~V} \sim 5 \mathrm{~V}$ |
|  | $3-02.2$ | $0 \mathrm{~V} \sim 10 \mathrm{~V}$ |
|  | $3-02.2$ | $\pm 5 \mathrm{~V}$ |

Reference 1. Simultaneous output is not used. Therefore the V-out output range settings are applied with priority during setting.
Reference 2 . When only using I-out, the V-out output range must be set to 0 .
Menu-F3.03: I-out range setting

| Function | I-out range |  |
| :---: | :---: | :--- |
| Set Range | Display Part | Meaning |
|  | $3-03.2$ | I-out is closed |
|  | $3-03.1$ | $4 \mathrm{~mA} \sim 20 \mathrm{~mA}$ |
|  | $3-03.2$ | $0 \mathrm{~mA} \sim 20 \mathrm{~mA}$ |
|  | $3-03.3$ | $0 \mathrm{~mA} \sim 24 \mathrm{~mA}$ |

## Menu-F3.04: Dual output(V-out \& I-out)

| Function | Dual output(V-out \& I-out) | Meaning |
| :---: | :---: | :--- |
| Set Range <br> $(0,1)$ | Display Part | Dual output disabled |
|  | 3-04. 0 | Dual output enabled |

## Menu-F3.05: Minimum weight of A-out

| Function | Minimum Output Weight Value upon Using Analog Out option |  |
| :---: | :---: | :--- |
| Set Range | Display Part | Meaning |
|  | 1000 | Maximum output at 1000 kg |
|  | 2000 | Maximum output at 2000 kg |
|  | Initial value:0 |  |

Menu-F3.06: Maximum weight of A-out

| Function | Maximum Output Weight Value upon Using Analog Out option |  |
| :---: | :---: | :---: |
|  | Display Part | Meaning |
| Set Range ( $0 \sim$ Max weight) | 1000 <br> 2000 <br> Initial value: Max weight | Maximum output at 1000 kg Maximum output at 2000 kg |

Menu-F3.07: Adjust zero of A-out

| Function | Adjust the Zero Output upon Using Analog Out option |  |
| :---: | :---: | :--- |
| Set Range | Display Part | Meaning |
|  | 0000 | $0.000 \mathrm{~mA}, 0 \mathrm{~V}$ output |
|  | $\mathbf{4 0 0 0}$ | $4.000 \mathrm{~mA}, 2 \mathrm{~V}$ output |
|  | 4015 | $4.015 \mathrm{~mA}, 2.007 \mathrm{~V}$ output |

Reference 1. The example is based on settings of $0 \sim 10 \mathrm{~V}, 0 \sim 24 \mathrm{~mA}$.
Reference 2. The Micro-adjustment function does not work during simultaneous output of V-out and I-out.

## Menu-F3.08: Adjust Span of A-out

| Function | Adjust the Maximum Output upon Using Analog Out option |  |
| :---: | :---: | :---: |
| Set Range | Display Part | Meaning |
|  | 10000 | 10.000 mA, |
|  | $\mathbf{2 0 0 0 0}$ | 4.16 V output |
|  | 24000 | $24.000 \mathrm{~mA}, \quad 8.33 \mathrm{~mA}, \quad 10.0 \mathrm{~V}$ output |
|  |  |  |

Reference 1. The example is based on settings of $0 \sim 10 \mathrm{~V}, 0 \sim 24 \mathrm{~mA}$.
Reference 2. The Micro-adjustment function does not work during simultaneous output of V-out and I-out.

### 9.5 Hardware Set Function

Menu-F4.01: Set Date

| Function | Set Date |  |  |
| :---: | :---: | :--- | :--- |
| Number Key | Display Part |  | Meaning |
| $:$ Data Designation | 10.08 .17 | August 17th, 2010 |  |

Menu-F4.02: Set Time

| Function | Set Time |  |
| :---: | :---: | :---: |
| Number Key | Display Part | Meaning |
| $:$ Data Designation | 11.30 .10 | 30 minutes and 10seconds past 11 o'clock |

## Menu-F4.03: Set Alibi memory

| Function | Set Alibi memory |  |
| :---: | :---: | :--- |
| Set Range <br> $(0,1)$ | Display Part | Meaning |
|  | 4-03. 0 | Alibi memory function is disable |
|  | $4-03.1$ | Alibi memory function is enable |

## Menu-F4.04: Set memory over writing

| Function | Set memory over writing |  |
| :---: | :---: | :--- |
| Set Range <br> $(0,1)$ | Display Part | Meaning |
|  | $4-04.0$ | Disable over writing of memory |
|  | $4-04.1$ | Enable over writing of memory |

### 9.6 Relay Setting

Menu-F5.01: Set Relay mode

| Function | Set Relay mode |  |  | Meaning |
| :---: | :---: | :--- | :---: | :---: |
| Set Range | Display Part | 5-01. 0 |  | Limit Mode |
|  | $5-01.1$ | Limit type Checker Mode |  |  |
|  | $5-01.2$ | Checker Mode |  |  |
|  | $5-01.3$ | Programmable Mode |  |  |

$<$ Limit Mode>


Note.

1. Set value input requirement: $\mathrm{SP} 2>\mathrm{SP} 1$
2. Relay Output

| Step $1: \mathrm{W} \geq \mathrm{SP1} \rightarrow \mathrm{ON}$ |
| :--- |
| Step $2: \mathrm{W} \geq \mathrm{SP2} \rightarrow \mathrm{ON}$ |
| Finish $: \mathrm{W} \geq$ SP2 \& Stable $\rightarrow \mathrm{ON}$ |
| Near zero $:$ Set value $\geq 0$ range output |

<Checker Mode>


Note.

1. Set value input requirement: $\mathrm{SP} 2>\mathrm{SP} 1$
2. Relay Output

| LOW : $\mathrm{SP} 1 \geq \mathrm{W} \rightarrow \mathrm{ON}$ |
| :--- |
| $\mathrm{HIGH}: \mathrm{W} \geq \mathrm{SP} 2 \rightarrow \mathrm{ON}$ |
| Finish(OK): $\mathrm{SP} 1<\mathrm{W}<\mathrm{SP} 2 \rightarrow \mathrm{ON}$ |
| Near zero: Set value $\geq 0$ range output |

<Limit type Checker Mode>


Note.

1. Set value input requirement: $\mathrm{SP} 2>\mathrm{SP} 1$
2. Relay Output

| LOW: $: \mathrm{SP1} \geq \mathrm{W} \rightarrow \mathrm{ON}$ |
| :--- | :--- |
| $\mathrm{HIGH}: \mathrm{W} \geq \mathrm{SP2} \rightarrow \mathrm{ON}$ |
| Finish $(\mathrm{OK}): \mathrm{SP1}<\mathrm{W}<\mathrm{SP} 2 \rightarrow \mathrm{ON}$ |
| Near zero: Set value $\geq 0$ range output |

3. Whenever stable, each output set.
4. No change the status until come back to the Zero Band
<Programmable Mode>


Note.

1. Set value input requirement: $\mathrm{SP} 4>\mathrm{SP} 3>\mathrm{SP} 2>\mathrm{SP} 1, \mathrm{SP} 5>\mathrm{SP} 6>\mathrm{SP} 7>\mathrm{SP} 8$
2. Relay Output

| Step $1: \mathrm{W} \geq \mathrm{SP} 1 \rightarrow \mathrm{ON}, \mathrm{W} \leq \mathrm{SP} 8 \rightarrow \mathrm{OFF}$ |
| :--- |
| Step $2: \mathrm{W} \geq \mathrm{SP} 2 \rightarrow \mathrm{ON}, \mathrm{W} \leq \mathrm{SP} 7 \rightarrow \mathrm{OFF}$ |
| Step 3:W $\geq \mathrm{SP} 3 \rightarrow \mathrm{ON}, \mathrm{W} \leq \mathrm{SP} 6 \rightarrow \mathrm{OFF}$ |
| Step $4: \mathrm{W} \geq \mathrm{SP} 4 \rightarrow \mathrm{ON}, \mathrm{W} \leq \mathrm{SP} 5 \rightarrow \mathrm{OFF}$ |

3. When it increases, External output ON. When it decreases, External output OFF

| Relay Mode | OUT 1 | OUT 2 | OUT 3 | OUT 4 |
| :---: | :---: | :---: | :---: | :---: |
| - 1_Limit Mode | Zero | $\begin{gathered} \text { Step 1 } \\ \mathrm{SPl} \leq \mathrm{W} \end{gathered}$ | $\begin{gathered} \text { Step 2 } \\ \text { SP2 } \leq \mathrm{W} \end{gathered}$ | Finish(Stable) |
| - 2_Limit type Checker Mode | Zero | $\begin{gathered} \text { LOW } \\ \mathrm{W} \leq \mathrm{SP} 1 \end{gathered}$ | $\begin{gathered} \mathrm{HIGH} \\ \mathrm{SP} 2 \leq \mathrm{W} \end{gathered}$ | $\begin{gathered} \text { Finish(OK) } \\ \mathrm{SP} 1<\mathrm{W}<\mathrm{SP} 2 \end{gathered}$ |
| - 3_CheckerMode | Zero | $\begin{gathered} \text { LOW } \\ \mathrm{W} \leq \mathrm{SP1} \end{gathered}$ | $\begin{gathered} \mathrm{HIGH} \\ \mathrm{SP} 2 \leq \mathrm{W} \end{gathered}$ | $\begin{gathered} \text { Finish(OK) } \\ \mathrm{SP} 1<\mathrm{W}<\mathrm{SP} 2 \end{gathered}$ |
| - 4_Programmable Mode | $\begin{gathered} \text { Step } 1 \\ \mathrm{SPl} \leq \mathrm{W}(\mathrm{ON}) \\ \mathrm{W} \leq \mathrm{SP} 8 \text { (OFF) } \end{gathered}$ | $\begin{gathered} \text { Step2 } \\ \text { SP2 } 2 \mathrm{~W}(\mathrm{ON}) \\ \mathrm{W} \leq \mathrm{SP7} \text { (OFF) } \end{gathered}$ | $\begin{gathered} \text { Step } 3 \\ \text { SP3 } \leq \mathrm{W} \text { (ON) } \\ \mathrm{W} \leq \operatorname{SP} 6 \text { (OFF) } \end{gathered}$ | $\begin{gathered} \text { Step4 } \\ \text { SP4 } \leq \mathrm{W}(\mathrm{ON}) \\ \mathrm{W} \leq \mathrm{SP} 5 \text { (OFF) } \end{gathered}$ |

Menu-F5.02: Set Ext Input 1

| Function | Set Ext Input 1 |  |
| :---: | :---: | :--- |
| Set Range <br> $(0 \sim 4)$ | Display Part | Meaning |
|  | $\mathbf{5 - 0 2 . 0 0}$ | External In1 is zero key |
|  | $5-02.01$ | External In1 is tare/tareless key |
|  | $5-02.02$ | External In1 is print key |
|  | $5-02.03$ | Extemal In1 is hold key |
|  | $5-02.04$ | Extemal In1 is hold clearkey |

Menu-F5.03: Set Ext Input 2

| Function | Set Ext Input 2 |  |
| :---: | :---: | :--- |
| Set Range <br> $(0 \sim 4)$ | Display Part | Meaning |
|  | $5-03.00$ | External In2 is zero key |
|  | $\mathbf{5 - 0 3 . 0 1}$ | External In2 is tare/tareless key |
|  | $5-03.02$ | External In2 is print key |
|  | $5-03.03$ | Extemal In2 is hold key |
|  | $5-03.04$ | Extemal In2 is hold clearkey |

Menu-F5.04: Relay Reverse On/Off

| Function | Relay Reverse On/Off |  |  |
| :---: | :---: | :--- | :--- |
| Set Range <br> $(0,1)$ | Display Part |  | Meaning |
|  | 504. 00 | Relay Reverse OFF |  |
|  | 5-04. 01 | Relay Reverse ON |  |

Menu-F5.05: Relay Display On/Off

| Function | Relay Display On/Off |  |  |
| :---: | :---: | :--- | :--- |
| Set Range <br> $(0,1)$ | Display Part |  | Meaning |
|  | 5-05. 00 | Relay Display OFF |  |
|  | 5-05. 01 | Relay Display ON |  |

### 9.7 TCP IP

Menu-F6.01: Set use DHCP

| Function | tuse DHCP |  |
| :---: | :---: | :---: |
| Set Range $(0,1)$ | Display Part | Meaning |
|  | 6-01. 0 | Use DHCP |
|  | 6-01. 1 | Not use DHCP(Static) |

Menu-F6.02: Set TCP mode

| Function | Set TCP mode |  | Meaning |
| :---: | :---: | :--- | :--- |
| Set Range <br> $(0,1)$ | Display Part |  |  |
|  | $\mathbf{6 - 0 2 . 0}$ | Server mode |  |
|  | $6-02.1$ | Client mode |  |

## Menu-F6.03: Set EXI-200(Server)IP

| Function | Set IP of Server |  |
| :---: | :---: | :--- |
| Set Range <br> $(0 \sim 255)$ | Display Part | Meaning |
|  | I1-.XXX | Set IP of 1st position(IP_V4) |
|  | I4-XXX | Set IP of 4th position(IP_V4) |
|  | Initial value :255 |  |

## Menu-F6.04: Set Subnet mask

| Function | Set Subnet mask |  |
| :---: | :---: | :--- |
| Set Range <br> $(0 \sim 255)$ | Display Part | Meaning |
|  | M1-.XXX | Set subnet mask of 1st position |
|  | M4-.XXX | Set subnet mask of 4th position |
|  | Initial value: 255 |  |

## Menu-F6.05: Set Gate way

| Function | Set Gate way |  |
| :---: | :---: | :--- |
| Set Range <br> $(0 \sim 255)$ | Display Part | Meaning |
|  | G1-.XXX | Set gate way of 1st position |
|  | G4-XXX | Set gate way of 4th position |
|  | Initial value :255 |  |

Menu-F6.06: Set EXI-200(Server) TCP Port

| Function | Set EXI-200(Server) TCP Port |  |
| :---: | :---: | :---: |
| Set Range$(0 \sim 65535)$ | Display Part | Meaning |
|  | 5000 | TCP port number $=5000$ |
|  | 20000 | TCP port number $=20000$ |
|  | Initial value: 20306 |  |

Menu-F6.07: Server TCP Output mode

| Function | Server TCP Output mode |  |
| :---: | :---: | :--- |
| Set Range <br> $(0 \sim 8)$ | Display Part | Meaning |
|  | $\mathbf{6 - 0 7 .} \mathbf{0}$ | Data is not transmitted |
|  | $6-07.1$ | Transmitted only if the print key is pushed |
|  | $6-07.2$ | Transmitted in both stable/unstable cases (Stream Mode) |
|  | $6-07.3$ | Transmitted only if the weight is stable |
|  | $6-07.4$ | Command Type 1 |
|  | $6-07.5$ | Command Type 2 |
|  | $6-07.6$ | Command Type 3 |
|  | $6-07.7$ | Transmitted only upon completion signal |
|  | $6-07.8$ | Modbus protocol |

Reference 1. For command types refer to Appendix 2, 3 and 4.
Reference 2. Communication format $=$ Set values of F2.06 applied.

Menu-F6.08: Set IP of Client

| Function | Set IP of Client |  |
| :---: | :---: | :--- |
| Set Range <br> $(0 \sim 255)$ | Display Part | Meaning |
|  | I1-.XXX | Set IP of 1st position(IP_V4) |
|  | I4-XXX | Set IP of 4th position(IP_V4) |
|  | Initial value: $\mathbf{2 5 5}$ |  |

Menu-F6.09: TCP port of Client

| Function | TCPport of Client |  |
| :---: | :---: | :--- |
| Set Range <br> $(0 \sim 99999)$ | Display Part | Meaning |
|  | 5000 | TCP port nubmer=5000 |
|  | 20000 | TCP port number $=20000$ |
|  | Initial value: $\mathbf{2 0 3 0 6}$ |  |

Menu-F6.10: Client TCP Output mode


Reference 1. For command types refer to Appendix 2, 3 and 4.
Reference 2. Communication format $=$ Set values of F2.06 applied.

### 9.8 Print Function Setting

Menu-F7.01: Set Printer Type

| Function | Set Printer Type |  |
| :---: | :---: | :--- |
| Set Range <br> $(0 \sim 3)$ | Display Part | Meaning |
|  | $7-01.0$ | Printer is not used |
|  | $7-01.1$ | CAS DEP Ticket Print Standard Type |
|  | $7-01.2$ | CAS DLP Label Print Standard Type |
|  | $7-01.3$ | CAS BP Label Printer |

Menu-F7.02: Set Print Form

| Function | Set Print Form |  |
| :---: | :---: | :---: |
| Set Range$(0 \sim 7)$ | Display Part | Meaning |
|  | 7-02. 0 | Print Form 1 (Date, Time, Serial No., Item No., Net Weight) BP Print Form 1(FORM1) |
|  | 7-02. 1 | Print Form 2 (Date, Time, Weighing No., Net Weight) BP Print Form 2(FORM2) |
|  | 7-02. 2 | Print Form 3 (Date, Time, Gross Weight, Tare, Net Weight) BP Print Form 3(FORM3) |
|  | 7-02. 3 | Print Form 4 (Date, Time, Net Weight) BP Print Form 4(FORM4) |
|  | 7-02. 4 | Print Form 5 (Date, Time, Item No., Net Weight) BP Print Form 5(FORM5) |
|  | 7-02. 5 | Print Form 6(Date, Time, Serial No., Net Weight) BP Print Form6(FORM6) |
|  | 7-02. 6 | Print Form 7 (Date, Time, Item Name, Item No., Net Weight) BP Print Form 7(FORM7) |
|  | 7-02. 7 | Print Form 6 (Date, Time, Item Name, Net Weight) BP Print Form 8(FORM8) |

［ Form 1 ］
Date，Time，
Serial No．，Item No．，Net Weight


## ［ Form 5 】

Date，Time，
Item No．，Net Weight
2009．07．07TTUE 12：30：46 ID＿11，Net：$\quad 50.0 \mathrm{~kg}$
ID＿12，Net：$\quad 100.0 \mathrm{~kg}$ ID＿19，Net：$\quad 200.5 \mathrm{~kg}$
［ Form 8 】
Date，Time，
Item Name．，Net Weight
Item No．，Net Weight
2009．07．07［TUE］12：30：46 Cement ID＿11，Net： 50.0 kg Cement ID＿11，Net： 50.0 kg

| 2009．07．07TUE $12: 30: 46$ |  |  |
| :--- | :---: | :---: |
| No． | 1 | 50.0 kg |
| No． | 2 | 100.0 kg |
| No． | 3 | 200.5 kg |

［Form2】
Date，Time，
Weighing No．，Net Weight
［ Form 7 】
Date，Time，
Item Name

| 2009．07．07［TUE］ |  | $12: 30: 46$ |
| :--- | :--- | :--- |
| Cement |  |  |
| ID＿11， | Net： | 50.0 kg |
| Cement |  |  |
| ID＿11， | Net： | 50.0 kg |

［ Form3 ］
Date，Time，
Gross Weight，Tare，Net Weight

| 2009．07．07TUE］ $12: 30: 46$ |  |
| :---: | ---: |
| Gross： | 1000.0 kg |
| Tare ： | 0.0 kg |
| Net ： | 1000.0 kg |
| Gross： | 200.0 kg |
| Tare ： | 500.0 kg |
| Net $:$ | 1500.0 kg |
|  |  |
|  |  |

［ Form 6 】
Date，Time，
Serial No．，Net Weight

$\square$ CAS DLP Protocol

| Parameter | Description | Data Length |
| :---: | :--- | :--- |
| V00 | Gross Weight | 7 byte |
| V01 | Tare Value | 7 byte |
| V02 | Net Weight | 7 byte |
| V03 | Barcode (net weight) | 6 byte |
| V04 | Item Number | 2 byte |
| V05 | Item Name | 10 byte |
| V06 | Print count | 3 byte |
| V07 | Date | 10 byte |
| V08 | Time | 8 byte |

$\square$ CAS BP Series Printer Protocol

| Parameter | Description | Data Length |
| :---: | :--- | :--- |
| V00 | Gross Weight | 7 byte |
| V01 | Tare Value | 7 byte |
| V02 | Net Weight | 7 byte |
| V03 | Net (‘'‘omit) : for bar code | 6 byte |
| V04 | Item Number | 2 byte |
| V05 | Item Name | 10 byte |
| V06 | Print count | 3 byte |
| V07 | Date | 10 byte |
| V08 | Time | 8 byte |
| V09 | Unit(kg) | 2 byte |
| V10 | Total Net (‘.' include) | 9 byte |
| V11 | Preset Tare | 7 byte |
|  |  |  |

Menu-F7.03: Manage Print Data

| Function | Manage Print Data |  |
| :---: | :---: | :--- |
| Set Range <br> $(0 \sim 1)$ | Display Part | Meaning |
|  | $7-03.0$ | Accumulated value is cleared upon printing |
|  | $7-03.1$ | Cleared when the clearing key is pushed |

Menu-F7.04: Set Print Line feed

| Function | Set Print Line feed |  |
| :---: | :---: | :---: |
| Set Range <br> (0-9) | Display Part |  |
|  | 7-04. 1 |  |
|  | Set a spacing between lines as the set value upon printing |  |

Menu-F7.05: Set Print Head Message


Reference 1. This function adds the desired content to the print format. (e.g.: company name, phone number)
Reference 2. Coordinates capable of being designated are from 0 to 71 . From these, the 0 th data determines whether to print the additional content (032: print, all others: do not print) and everything is printed from data 1 until data 255.
Reference 3 . To add company name "CAS" to the existing print format, designate as follows
P00-032 (ASCII code 32: data starts), P01-067 (ASCII code 67: character C) P02-065 (ASCII code 65: character A) P03-083 (ASCII code 83: character S) P04-255 (ASCII code 255: data ends)

Menu-F7.06: Set Printing Delay Time

| Function | Set Printing Delay Time |  |  |
| :---: | :---: | :--- | :--- |
| Set Range <br> $(0 \sim 200)$ | Display Part | $7-06.1$ <br> Initial Value: 1 |  |
|  | Issue print after 00 x 10ms | Meaning |  |

Menu-F7.07: Set Print Condition

| Function | Set Print Condition |  |
| :---: | :---: | :--- |
| Set Range <br> $(0 \sim 2)$ | Display Part | Meaning |
|  | $7-07.0$ | Print out only if the weight value is + |
|  | $7-07.1$ | Print out only if the weight value is - |
|  | $7-07.2$ | Print out regardless of whether the weight value is $+/-$ |

Menu-F7.08: Set Print Out Condition

| Function | Set Print Out Condition (Printing condition) |  |
| :---: | :---: | :--- |
| Set Range <br> $(0 \sim 1)$ | Display Part | Meaning |
|  | 7-08. 0 | Printed only if the print key is pushed |
|  | $7-08.1$ | Printed automatically if the weight value is stabilized |

## Menu-F7.09: Print Count Number

| Function | Print Count Number |  |
| :---: | :---: | :--- |
| Set Range <br> $(0 \sim 1)$ | Display Part | Meaning |
|  | $7-09.0$ | Fixed |
|  | $7-09.1$ | Printing times are increased automatically by one at a time <br> after weighing operation |

## 10. Error Message

### 10.1 Errors that can occur in weight calibration mode

| Error | Cause | Solution |
| :---: | :--- | :--- | \left\lvert\, \(\left.\begin{array}{l}Err 20 <br>

\hline The set resolution has exceeded the <br>
allowance limit of 1/30,000.\end{array} $$
\begin{array}{l}\text { Lower resolution. } \\
\text { Resolution = maximum allowed weightvalue of 1 increment. } \\
\text { Adjust maximumallowed weight inCAL 1 of weight calibration } \\
\text { mode or adjust the value of 1 incrementinCAL 3 of weight } \\
\text { calibration mode to adjust to below 1/30,000. }\end{array}
$$\right.\right\}\)

### 10.2 Errors that can occur in weighing mode

| Error | Cause | Solution |
| :--- | :--- | :--- |
| Err 01 | Due to unstable load the weighing scale cannot <br> be reset. | Move the weighing scale to a flat, vibration-free <br> surface and turn on the power. |
| Err 02 | Load cell is not properly connected or there is a <br> problem with the AD convertor. | Check if the main body and the load plate are <br> connected properly. |
| Err 08 | The zero-set key, container key and start key are <br> set not to function when the load is unstable. | In F22 of the Conversion Mode, set the zero-set key, <br> container key and start key activation conditions <br> based on the environment of use. |
| Err 09 | The current weight exceeds the zero-set range. | In F09 of Conversion Mode set the activation range <br> to within 2\% or 10\% of the maximum capacity. |
| Err 10 | The weight of the container being designated <br> exceeds the maximum capacity of the weighing <br> scale. | Set the container weight to be less than the maximum <br> capacity. |
| Err 13 | When calibrating the weight the set zero-set has <br> been exceeded. | Check the status of the load plate and redo the weight <br> calibrations. |
| Err 15 | In Command Mode, the Item Code has <br> exceeded the set range. | Check the Item Code range |
| Err 82 | There is a problem with the A/D convertor. | Please contact the A/S center. |
| OVER | The current load on the load plate is too heavy, <br> and exceeds the allowance limit. | Donot place weight exceeding the capacity limit on <br> the weighing scale. If the load cell is damaged, it <br> must be replaced. |

## Appendix 1> Data format

* 22 Bytes for CAS


Device ID: Send ing1 byte of device ID to selectively receive the information from the indicator to the receiver. (Device ID is set in F20.)

Lamp Status Byte

| Bt7 <br> 1 | Bt6 <br> Stable | Bt5 <br> 1 | Bt4 <br> Hold | Bt3 <br> Printer | Bt2 <br> Gross <br> Weight | Bt1 <br> Tare | Bt0 <br> Zero <br> Point |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |

* 10 Bytes for CAS

| Data (8bytes) | CR | LF |
| :--- | :--- | :--- |

* 18 Bytes for AND

* 22 Bytes for CAS (Relay status)

- Relay status bytes

| Bt7 | Bt6 | Bt5 | Bt4 | Bt3 | Bt2 | Bt1 | Bt0 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Out8 | Out7 | Out6 | Out5 | Out4 | Out3 | Out2 | Out1 |

*Weight Date (8 byte)

| Example weight | Byte No |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 |
| 13.5 kg | '، | ، ، | ، ${ }^{\prime}$ | '، | '1' | '3' | '.' | '5' |
| 135 kg | ، ${ }^{\text {d }}$ | ، ${ }^{\text {d }}$ | '، | '، | '1' | '3' | '5' | ، |
| -135kg | '-‘ | ، ${ }^{\text {c }}$ | ، ${ }^{\prime}$ | ، | '1' | '3' | '5' | ، ${ }^{\prime}$ |

## Appendix 2> Command Mode 1 Description

## CAS $<$ NT-500 Command>

| Indicator Reception | Function | Indicator Response |
| :--- | :--- | :--- |
| dd RW CR LF | Request for Weight Data | Transmit the data in the set format upon command input |
| dd MZ CR LF | Same as Zero Key | Execeute the zero and retransmit dd MZ CR LF to PC <br> upon command input |
| ddMTCR LF | Same as Tare Key | Execeute tare and retransmit dd MT CR LF to PC upon <br> command input |
| dd PN 00 CR LF | Input Item No.(00-50) | Change the item no. and retransmit dd PN 00 <br> CR LF to PC upon command input. |
| dd OP CR LF | Same as Start Key | Execute the start and retransmit dd OP CR LF <br> to PC upon command input |
| ddEMCR LF | Same as Stop Key | Execute the stop and retransmit dd EMCR LF <br> to PC upon command input |

* dd : Device ID. (ASCII Code : $0 \times 30$ (hex), $0 \times 31$ (hex if the Device ID is " 01 ")
* 00000,00 : Set value for upper limit/lower limit/upper limit fall/lower limit fall
(ASCII Code : 0x30(hex), 0x30(hex), 0x33(hex), 0x34(hex),

$$
0 \times 35 \text { (hex) if the set value is " } 00345 \text { ") }
$$

* When it fails to execute the command : ! CR LF is transmitted to the computer.
* When there is an error in the command : ? CR LF is transmitted to the computer.


## Appendix 3> Command Mode 2 Description

## CAS < NT-570 Command>

Reference 1. Command Mode Table

| Command data to NT-570A |  |  |  |  |  |  |  |  |  |  | Command description | NT-570A Respond |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 0 | 12 | 3 | 4 | 5 | 6 | 7 | 8 | 9 | 10 | 11 |  |  |
| D | ID | K | Z | CR | LF |  |  |  |  |  | ZERO key |  |
| D | ID | K | T | CR | LF |  |  |  |  |  | TARE key | Return the received |
| D | ID | K | G | CR | LF |  |  |  |  |  | GROSS key | Return the received |
| D | ID | K | N | CR | LF |  |  |  |  |  | NET key | Return the received |
| D | ID | K | S | CR | LF |  |  |  |  |  | START key | Return the received |
| D | ID | K | P | CR | LF |  |  |  |  |  | STOP key | Return the received |
| D | ID | K | B | CR | LF |  |  |  |  |  | Print key | Return the received |
| D | ID | K | C | CR | LF |  |  |  |  |  | Total print key | Return the received |
| D | ID | K | W | CR | LF |  |  |  |  |  | Request weight data | Return the received |
| D | ID | H | T | CR | LF |  |  |  |  |  | Request set point value | Send Format 2 |
| D | ID | S | 1 | 0 | 0 | 0 | 0 | 0 | CR | LF | $1^{\text {s }}$ Step value | Return the received |
| D | ID | S | 2 | 0 | 0 | 0 | 0 | 0 | CR | LF | 2nd Step value | Return the received |
| D | ID | S | 3 | 0 | 0 | 0 | 0 | 0 | CR | LF | 3rd Step value | Return the received |
| D | ID | S | 4 | 0 | 0 | 0 | 0 | 0 | CR | LF | 4th Step value | Return the received |
| D | ID | S | 5 | 0 | 0 | 0 | 0 | 0 | CR | LF | High limit value | Return the received |
| D | ID | S | 6 | 0 | 0 | 0 | 0 | 0 | CR | LF | Low limit value | Return the received |
| D | ID | H | E | 0 | 0 | 0 | 0 | 0 | CR | LF | Set point code(00-99) | Return the received |

(D, ID:00-99, CR : $0 \times 13$, LF: $0 \times 10$ )

* Format $1:$ PC send set point all data to indicator NT-580A

| 0 | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 | 10 | 11 | 12 | 13 | 14 | 15 | 16 | 17 | 18 | 19 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| D | ID |  | H | A | Set Point code |  |  |  |  | , | SP | SP | SP | SP | SP | " | Optional- |  |  |
| 20 | 21 | 22 | 23 | 24 | 25 | 26 | 27 | 28 | 29 | 30 | 31 | 32 | 33 | 34 | 35 | 36 | 37 | 38 | 39 |
|  |  | , | Preliminary |  |  |  |  | , | Final value |  |  |  |  | , | FreeFall |  |  |  |  |
| 40 | 41 | 42 | 43 | 44 | 45 | 46 | 47 | 48 | 49 | 50 | 51 | 52 | 53 |  |  |  |  |  |  |
| , | High limit |  |  |  |  | , | Low limit |  |  |  |  | CR | LF |  |  |  |  |  |  |

* Format 2 : Recieve the request data from $P C$ then response of Indicator

| 0 | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 | 10 | 11 | 12 | 13 | 14 | 15 | 16 | 17 | 18 | 19 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| D | ID |  | H | T | SetPoint code |  |  |  |  | , | SP | SP | SP | SP | SP | " | Optional- |  |  |
| 20 | 21 | 22 | 23 | 24 | 25 | 26 | 27 | 28 | 29 | 30 | 31 | 32 | 33 | 34 | 35 | 36 | 37 | 38 | 39 |
|  |  | , | Preliminary |  |  |  |  | , | Final value |  |  |  |  | , | Free Fall |  |  |  |  |
| 40 | 41 | 42 | 43 | 44 | 45 | 46 | 47 | 48 | 49 | 50 | 51 | 52 | 53 |  |  |  |  |  |  |
| , | High limit |  |  |  |  | , | Lowlimit |  |  |  |  | CR | LF |  |  |  |  |  |  |

[^2]
## Appendix 4> Command mode 3 Description

CI-5000 : Transmission only if data is requested ( 1 byte communication)

## Appenix 5> ASCII Table

| CHA | CODE | CHA | CODE | CHA | CODE | CHA | CODE | CHA | CODE | CHA | CODE |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Space | 32 | 0 | 48 | @ | 64 | P | 80 |  | 96 | p | 112 |
| ! | 33 | 1 | 49 | A | 65 | Q | 81 | a | 97 | q | 113 |
| " | 34 | 2 | 50 | B | 66 | R | 82 | b | 98 | r | 114 |
| \# | 35 | 3 | 51 | C | 67 | S | 83 | c | 99 | s | 115 |
| \$ | 36 | 4 | 52 | D | 68 | T | 84 | d | 100 | t | 116 |
| \% | 37 | 5 | 53 | E | 69 | U | 85 | e | 101 | u | 117 |
| \& | 38 | 6 | 54 | F | 70 | V | 86 | f | 102 | v | 118 |
| - | 39 | 7 | 55 | G | 71 | W | 87 | g | 103 | w | 119 |
| ( | 40 | 8 | 56 | H | 72 | X | 88 | h | 104 | x | 120 |
| ) | 41 | 9 | 57 | I | 73 | Y | 89 | i | 105 | y | 121 |
| * | 42 | : | 58 | J | 74 | Z | 90 | j | 106 | z | 122 |
| + | 43 | ; | 59 | K | 75 | [ | 91 | k | 107 | \{ | 123 |
| , | 44 | < | 60 | L | 76 | 1 | 92 | 1 | 108 | \| | 124 |
| - | 45 | $=$ | 61 | M | 77 | ] | 93 | m | 109 | \} | 125 |
| . | 46 | > | 62 | N | 78 | $\wedge$ | 94 | n | 110 | $\sim$ | 126 |
| 1 | 47 | ? | 63 | O | 79 | - | 95 | 0 | 111 | End | 0 |

## Appendix 6>MODBUS-RTU PROTOCOL

The registry read and write shown below of MODBUS-RTU protocol can be managed based on the requirements included in the reference document regarding the Modicon PI-MBUS-300 standard.
For selection of communication with Modbus-RTU, the serial communication settings paragraph has been included.
If specific data has been recorded directly in EEPROM type memory, it is recommended that unnecessary work at the aforementioned position be avoided as the memory is limited in its write activation $(100,000)$.
The below number is, when coming after 0 x , is described in a decimal or a hexadecimal method.

## MODBUS-RTU DATA FORMAT

Data transferred by the Modbus-RTU protocol has the following characteristics.

- Start bit 1
- Data bit 8 (smallest bit sent first)
- Parity bit setting (instrument setting)
- Stop bit setting (instrument setting)


## MODBUS SUPPORTED FUNCTIONS

From the commands capable of being used in the Modbus-RTU protocol, only the following are used in communication management with the instrument. Other commands may not be accurately interpreted and may cause error or shutdown the system.

| Function | Explanation |
| :---: | :---: |
| $03(0 \times 03)$ | READ HOLDING REGISTER |
| $16(0 \times 10)$ | PRESET MULTIPLE REGISTERS |

The request cycle is integrated with the preset communication speed. (The instrument requires a transfer delay of at least 3 bytes to reply to the request)
Delay parameters exist in the serial communication setting, and directly affect the number of request possible in a unit time by additionally delaying the reply from the instrument.
For additional information about this protocol, refer to the PI_MBUS_300 normal technical specifications.
Typically, the request and reply for the slave instrument is composed as follows.

## FUNCTION 3: Read holding registers

## Request

| Address | Funcion | Register1 <br> Address | No. register | 2 bytes |
| :---: | :---: | :---: | :---: | :---: |
| A | $0 \times 03$ | $0 \times 0000$ | $0 \times 0002$ | CRC |

Total. bytes $=8$

## Reply

| Address | Funcion | No.bytes | Register1 | Register2 | 2 bytes |
| :---: | :---: | :---: | :---: | :---: | :---: |
| A | $0 \times 03$ | $0 \times 04$ | $0 \times 0064$ | $0 \times 00 \mathrm{C} 8$ | CRC |

Total. bytes $=3+2 *$ No. register +2
-number of register $=$ number of modbus register to be read, start at address 1 register.
-number of byte = number of bytes in the following data

## FUNCTION 16: Preset multiple registers

## Request

| Addr | Funcion | Add. <br> Reg.1 | No.reg. | No. bytes | Val. Reg. <br> 1 | Val. Reg. <br> 2 | 2 bytes |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| A | $0 \times 10$ | $0 \times 0000$ | $0 \times 0002$ | $0 \times 4$ | $0 \times 0000$ | $0 \times 0000$ | CRC |

Total. bytes $=7+2 *$ No. register +2

## Reply

| Address | Funcion | Add.Reg.1 | No.reg. | 2 bytes |
| :---: | :---: | :---: | :---: | :---: |
| A | $0 \times 10$ | $0 \times 0000$ | $0 x 0002$ | CRC |

Total. bytes $=8$
-No. registers $=$ number of modbus register to be read, start at address 1 register
-No. bytes $=$ Number of following data bytes
-Val.reg. $1=$ Content of starting register In the reply, the number of converted redcodes starting from address 1 is included.

## Communication Error Management

The management of communication data error must be controlled by CRC (cycle redundancy check).

If a communication error occurs, the slave does not reply to any request.
The master must consider the time-out before receiving the reply. If no reply is received, it can be inferred that a communication error has occurred.

If the data strings have been accurately received but cannot be executed, an exceptional response is required. The contents are as follows.

## Exceptional response

| Address | Function | Code | 2bytes |
| :---: | :---: | :---: | :---: |
| A | Funct $+0 \times 80$ |  | CRC |


| CODE | DESCRIPTION |
| :---: | :--- |
| 1 | Invalid or unsupported function (ILLEGAL FUNCTION) |
| 2 | When the stated data address cannot be used (ILLEGAL DATA ADDRESS) |
| 3 | When the received data value is invalid (ILLEGAL DATA VALUE ) |
| 4 | Error in the CRC code (CRC Error) |

## Register List

The Modbus-RTU protocol registers capable of being executed in this instrument are as follows.
$\mathbf{R}=$ Register that can be used as read-only
$\mathbf{W}=$ Register that can be used as write-only
R/W = Register that can be used as for both read and write
$\mathbf{H}=$ Higher word of the Double word composing the register
$\mathbf{L}=$ Lower word of the Double word composing the register

| REGISTER | DESCRIPTION | Input value | Saving to <br> EEPROM | ACCES S |
| :---: | :---: | :---: | :---: | :---: |
| 40002 | Type of instrument | - | - | R |
| 40008 | GROSS WEIGHT H | - | - | R |
| 40009 | GROSS WEIGHT L | - | - | R |
| 40010 | NET WEIGHT H | - | - | R |
| 40011 | NET WEIGHT L | - | - | R |
| 40014 | Raw AD Data_H | - | - | R |
| 40015 | Raw AD Data_L | - | - | R |
| 40017 | Set point 1 H | 0~99999 | Y | R/W |
| 40018 | Set point 1 L | 0~99999 | Y | R/W |
| 40019 | Set point 2 H | 0~99999 | Y | R/W |
| 40020 | Set point 2 L | 0~99999 | Y | R/W |
| 40021 | Set point 3 H | 0~99999 | Y | R/W |
| 40022 | Set point 3L | 0~99999 | Y | R/W |
| 40023 | Set point 4H | 0~99999 | Y | R/W |
| 40024 | Set point 4L | 0~99999 | Y | R/W |
| 40037 | Ext_Input | - | - | R/W |


| 40038 | Ext_Output | - | - | R/W |
| :---: | :---: | :---: | :---: | :---: |
| 40042 | Analog out Span Weight H | 0~99999 | Y | R/W |
| 40043 | Analog out Span Weight L | 0~99999 | Y | R/W |
| 40044 | Analog out Zero Adjust H | 0~99999 | Y | R/W |
| 40045 | Analog out Zero Adjust L | 0~99999 | Y | R/W |
| 40046 | Analog out Span Adjust H | 0~99999 | Y | R/W |
| 40047 | Analog out Span Adjust L | 0~99999 | Y | R/W |
| 40050 | Analog Out V-Out range Setting | 0~99999 |  |  |
| 40051 | Analog Out l-Out range Setting | 0~99999 |  |  |
| 40052 | Analog Out Dual-Out range Setting | 0~99999 |  |  |
| 40060 | ADC Speed | 0~99999 | Y | R/W |
| 40062 | AD Filter Size | 0~99999 | Y | R/W |
| 40063 | Set Low pass filter | $\begin{gathered} \text { 0: OFF } \\ \text { 1:ON } \\ \hline \end{gathered}$ | Y | RW |
| 40064 | Order of Low pass filter | 2~4 | Y | RW |
| 40065 | Cut frequency of Low pass filter | 1~100 | Y | RW |
| 40066 | Set Band stop filter | $\begin{gathered} 0: \text { OFF } \\ \text { 1:ON } \end{gathered}$ | Y | RW |
| 40067 | High cut Frequency of Band stop filter | 1~100 | Y | RW |
| 40068 | Low cut Frequency of Band stop filter | 1~100 | Y | RW |
| $\begin{gathered} 40069 \\ \sim \\ 40080 \\ \hline \end{gathered}$ | Reserved |  | - | - |
| 40053 | Ext_Input |  | Y | R/W |
| 40060 | Ext_Output |  | Y | R/W |
| 40062 | Analog out Span Weight H |  | Y | R/W |
| 40063 | ADC reserved |  | - | - |
| 40064 | ADC reserved |  | - | - |
| 40065 | ADC reserved |  | - | - |


| 40066 | ADC reserved |  | - | - |
| :---: | :---: | :---: | :---: | :---: |
| 40067 | ADC reserved |  | - | - |
| 40068 | ADC reserved |  | - | - |
| 40081 | Stable range | 0~99 | Y | R/W |
| 40082 | Zero tracking range | 0~9 | Y | R/W |
| 40083 | Weight back up | $\begin{gathered} \text { 0: OFF } \\ \text { 1:ON } \end{gathered}$ | Y | R/W |
| 40084 | Zero key range | 0~99 | Y | R/W |
| 40085 | Tare key range | 0~99 | Y | R/W |
| 40086 | Initial zero range | 0~99 | Y | R/W |
| 40087 | Overload range | 0~9 | Y | R/W |
| 40088 | reserved |  | - | - |
| 40089 | Zero, Tare, Gross/Net, Hold, Tare Clear, Hold Clear | 1 : Zero <br> 2 : Tare <br> 3 : Gross/Net <br> 4 : Hold <br> 5: Tare Clear <br> 6: Hold Clear | Y | W |
| 40090 | reserved |  | - | - |
| 40151 | Device Number |  | Y | R/W |
| 40152 | Comm transmit time |  | Y | R/W |
| 40153 | COM1's parity bit |  | Y | R/W |
| 40154 | COM1's Baudrate |  | Y | R/W |
| 40155 | COM1's output data(Gross/Net) |  | Y | R/W |
| 40156 | COM1's output format |  | Y | R/W |
| 40157 | COM1's output mode |  | Y | R/W |
| $\begin{gathered} 40158 \\ \sim \\ 40170 \\ \hline \end{gathered}$ | reserved |  | - | - |
| 40171 | Set Year |  | Y | R/W |
| 40172 | Set Month |  | Y | R/W |


| 40173 | Set Date |  | Y | R/W |
| :---: | :---: | :---: | :---: | :---: |
| 40174 | Set Hour |  | Y | R/W |
| 40175 | Set Minute |  | Y | R/W |
| 40176 | Set Second |  | Y | R/W |
| 40177 | Set use Alibi memory |  | Y | R/W |
| $\begin{aligned} & 40178 \\ & \tilde{\sim} \\ & 40199 \end{aligned}$ | reserved |  | - | - |
| 40200 | $\begin{aligned} & \hline \text { Local IP1 } \\ & (000 . \mathrm{XXX} . \mathrm{XXX} . \mathrm{XXX}) \\ & \hline \end{aligned}$ | 0~255 | Y | R/W |
| 40201 | $\begin{aligned} & \text { Local IP2 } \\ & (X X X .000 . ~ X X X . ~ X X X) \end{aligned}$ | 0~255 | Y | R/W |
| 40202 | $\begin{aligned} & \text { Local IP3 } \\ & (X X X . X X X .000 . X X X) \end{aligned}$ | 0~255 | Y | R/W |
| 40203 | $\begin{aligned} & \text { Local IP4 } \\ & \text { (XXX. XXX. XXX. 000) } \end{aligned}$ | 0~255 | Y | R/W |
| 40204 | $\begin{aligned} & \text { Server IP1 } \\ & \text { (000. } \mathrm{XXX} . \mathrm{XXX} . \mathrm{XXX}) \end{aligned}$ | 0~255 | Y | R/W |
| 40205 | $\begin{aligned} & \text { Server IP2 } \\ & (X X X .000 . X X X . X X X) \end{aligned}$ | 0~255 | Y | R/W |
| 40206 | $\begin{aligned} & \text { Server IP3 } \\ & (X X X . X X X .000 . X X X) \end{aligned}$ | 0~255 | Y | R/W |
| 40207 | $\begin{aligned} & \text { Server IP4 } \\ & (X X X . X X X . X X X .000) \end{aligned}$ | 0~255 | Y | R/W |
| 40208 | Sub net mask1 <br> (000. XXX. XXX. XXX) | 0~255 | Y | R/W |
| 40209 | Sub net mask2 <br> (XXX. 000. XXX. XXX) | 0~255 | Y | R/W |
| 40210 | Sub net mask3 <br> (XXX. XXX. 000. XXX) | 0~255 | Y | R/W |
| 40211 | Sub net mask4 <br> (XXX. XXX. XXX. 000) | 0~255 | Y | R/W |
| 40212 | Gate way1 <br> (000. XXX. XXX. XXX) | 0~255 | Y | R/W |
| 40213 | Gate way2 (XXX. 000. XXX. XXX) | 0~255 | Y | R/W |


| 40214 | Gate way3 <br> $(X X X . ~ X X X . ~ 000 . ~ X X X) ~$ | $0 \sim 255$ | Y | RW |
| :---: | :--- | :---: | :---: | :---: |
| 40215 | Gate way4 <br> $(X X X . ~ X X X . ~ X X X . ~ 000) ~$ | $0 \sim 255$ | Y | RW |
| 40216 | Set DHCP | $0:$ OFF <br> $1:$ ON | Y | RW |
| 40217 | Set TCP/IP Mode <br> (Server mode, Client mode) | $0:$ Server <br> $1:$ Client | Y | RW |
| 40218 | Set Local Port Number | $0 \sim 65535$ | Y | RW |
| 40219 | Set Server Port Number | $0 \sim 65535$ | Y | RW |
| 40220 | Set Local Comm mode | $0 \sim 7$ | Y | RW |
| 40221 | Set Server Comm mode | $0 \sim 7$ | Y | RW |

MEMO

MEMO

## Explosion proof Indicator

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[^0]:    * If 5~24V voltage is applied to terminals IN1, IN2, signal is input into each Input unit.

[^1]:    Reference 1 . If the key sensitivity is set high, it may be sensitive to external noise.

[^2]:    * Please input without the decimal point.

